

Modeling of superconductors interacting with non-linear magnetic materials: 3D variational principles, force-free effects and applications

Enric Pardo, Milan Kapolka

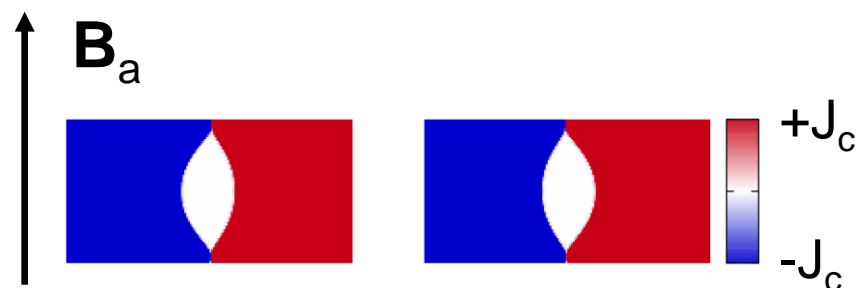
Institute of Electrical Engineering
Slovak Academy of Sciences



What is the optimum energy loss in superconductors?

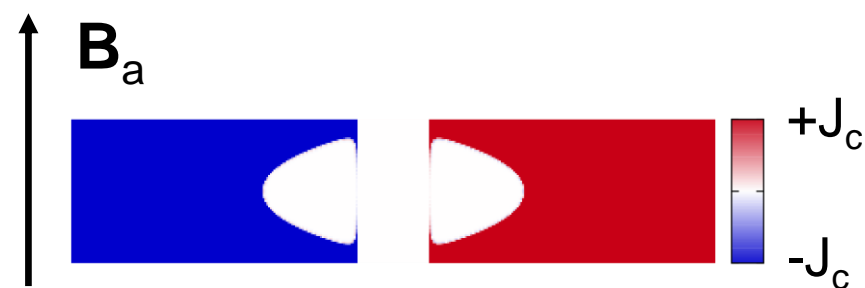
Two tapes connected at the ends

For you:



the lowest possible

For superconductors:



the highest possible!

Superconductors optimize the entropy production, not the loss!

Superconductors can be modelled as an optimization problem

Modeling of superconductors interacting with non-linear magnetic materials: **3D variational principles,** **force-free effects and applications**

Enric Pardo, Milan Kapolka

Institute of Electrical Engineering
Slovak Academy of Sciences



Modeling of superconductors interacting with non-linear magnetic materials: **3D variational principles,** force-free effects and applications

Enric Pardo, Milan Kapolka

Institute of Electrical Engineering
Slovak Academy of Sciences



We acknowledge funding from:



Talk available at **zenodo.org**

Citable DOI

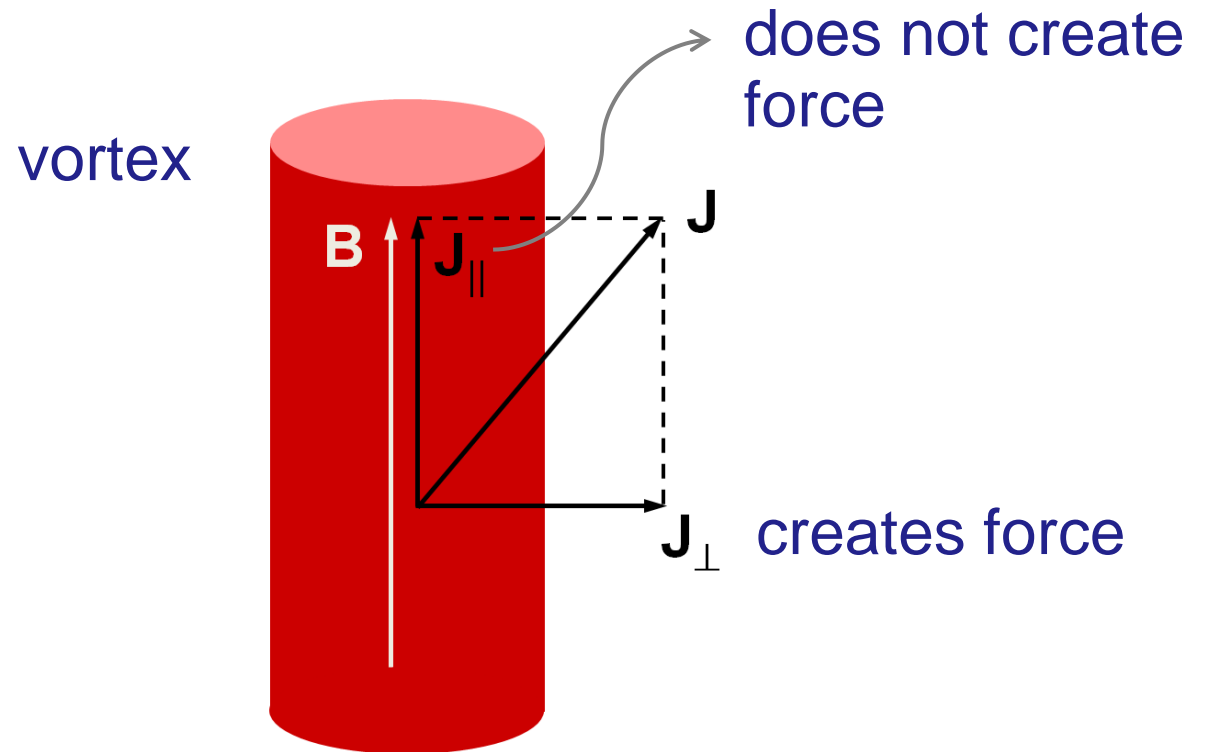
General variational principle

Power applications

3D modelling

Non-linear magnetic materials

Flux-free effects cause anisotropic $E(\mathbf{J})$



Two critical currents:

$\mathbf{J}_{c\perp}$

$\mathbf{J}_{c\parallel}$

Anisotropic power law:

$$\mathbf{E}(\mathbf{J}) = E_c \left[\frac{J_{\parallel}^2}{J_{c\parallel}^2} + \frac{J_{\perp}^2}{J_{c\perp}^2} \right]^{\frac{n-1}{2}} \cdot \left(\frac{J_{\parallel}}{J_{c\parallel}} \frac{J_{\perp}}{J_{c\parallel}} \mathbf{e}_{\parallel} + \frac{J_{\perp}}{J_{c\perp}} \mathbf{e}_{\perp} \right)$$

A Badia, C Lopez DOI: 10.1088/0953-2048/28/2/024003

Minimum Magnetic Entropy Production (MEMEP)

Equations

$$\mathbf{E}(\mathbf{J}) = -\frac{\Delta \mathbf{A}}{\Delta t} - \nabla \phi \quad \text{for given } \mathbf{E}(\mathbf{J}) \text{ relation}$$

$$\nabla \cdot \mathbf{J} = 0$$

are the Euler-Lagrange equations of

J change between two time instants

A from $\Delta \mathbf{J}$

A from applied field

scalar potential

$$L = \int_V dV \left[\frac{1}{2} \Delta \mathbf{J} \cdot \frac{\Delta \mathbf{A}_J}{\Delta t} + \Delta \mathbf{J} \cdot \frac{\Delta \mathbf{A}_a}{\Delta t} + U(\mathbf{J}) + \nabla \phi \cdot \mathbf{J} \right]$$

E Pardo et al. DOI: 10.1088/0953-2048/28/4/044003

A Bossavit DOI: 10.1109/20.312659

L Prigozin DOI: 10.1109/77.659440

A Badia, C Lopez DOI: 10.1088/0953-2048/28/2/024003

E Pardo and M Kapolka

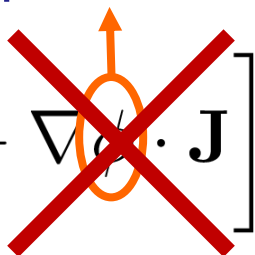
$$U(\mathbf{J}) = \int_0^{\mathbf{J}} d\mathbf{J}' \cdot \mathbf{E}(\mathbf{J})'$$

Minimum Magnetic Entropy Production (MEMEP)

You find \mathbf{J} by minimizing the functional

$$L = \int_V dV \left[\frac{1}{2} \Delta \mathbf{J} \cdot \frac{\Delta \mathbf{A}_J}{\Delta t} + \Delta \mathbf{J} \cdot \frac{\Delta \mathbf{A}_a}{\Delta t} + U(\mathbf{J}) + \cancel{\nabla \phi \cdot \mathbf{J}} \right]$$

scalar
potential



$$U(\mathbf{J}) = \int_0^{\mathbf{J}} d\mathbf{J}' \cdot \mathbf{E}(\mathbf{J})'$$

Cross-sectional models:

if you keep the current constrains,
you can ignore the scalar potential

E Pardo et al. DOI: 10.1088/0953-2048/28/4/044003

General variational principle

Power applications

Transformers

Magnets

3D modelling

Non-linear magnetic materials

General variational principle

Power applications

Transformers

Magnets

3D modelling

Non-linear magnetic materials

Transformer with Roebel cable in low-voltage winding

1 MVA 11 kV/415 V 3 phase transformer

Robinson Research Institute in Wellington
and industrial partners

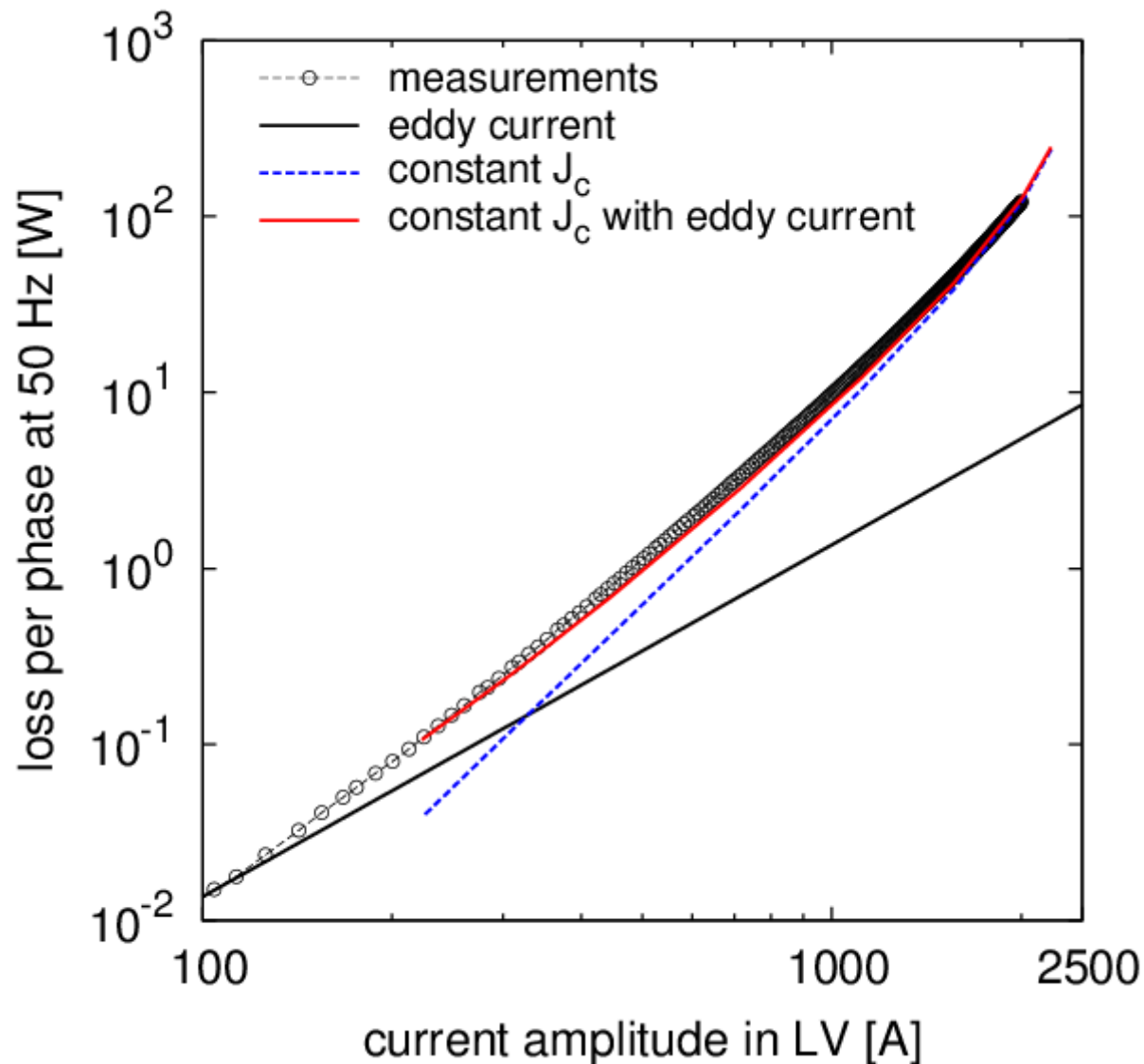


Roebel cable solenoid



AC loss agrees with model

E Pardo et al. DOI: 10.1088/0953-2048/28/11/114008



**Copper current leads
cause eddy current loss**

consistent
with estimations

Real large scale application

~1200 turns or strands

General variational principle

Power applications

Transformers

Magnets

- Real geometry
- Continuous approximation
- Screening current induced field

3D modelling

Non-linear magnetic materials

General variational principle

Power applications

Transformers

Magnets

- Real geometry
- Continuous approximation
- Screening current induced field

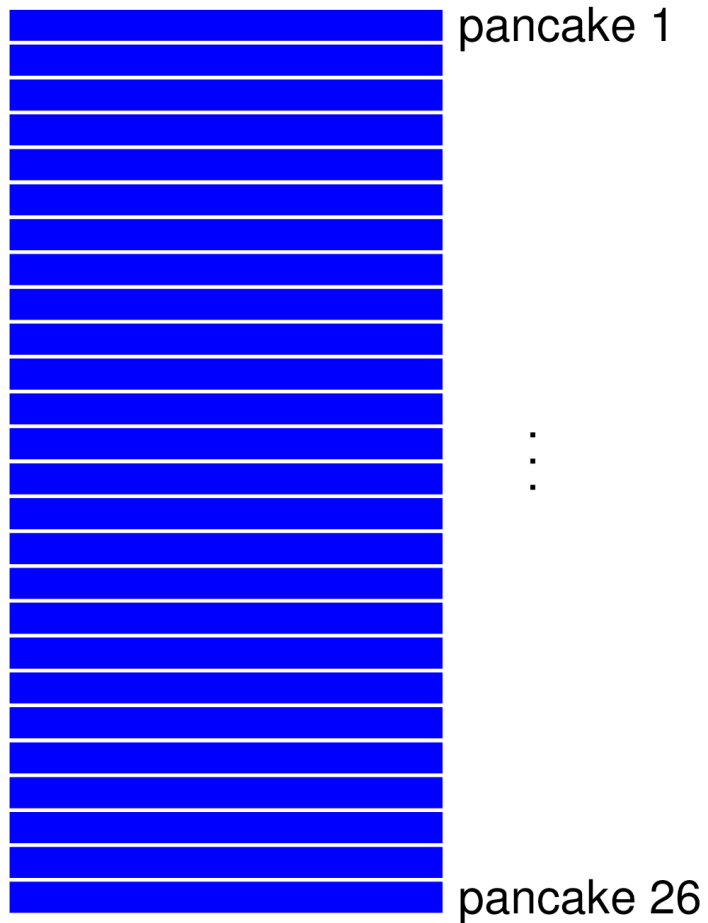
3D modelling

Non-linear magnetic materials

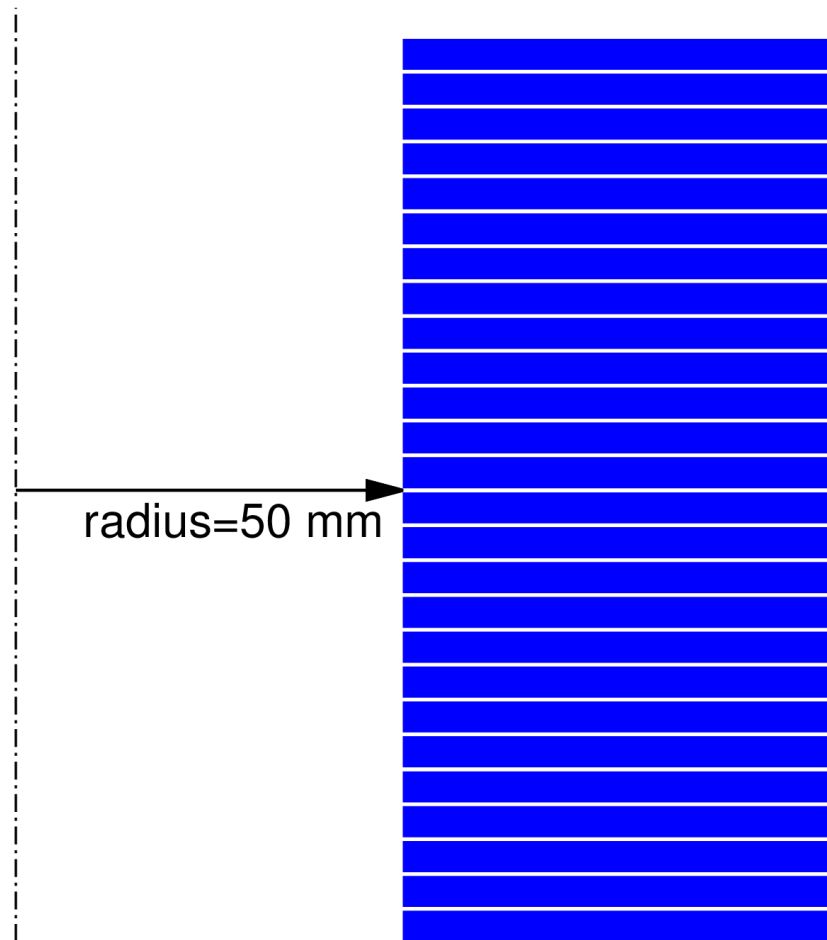
Example winding

26 pancakes

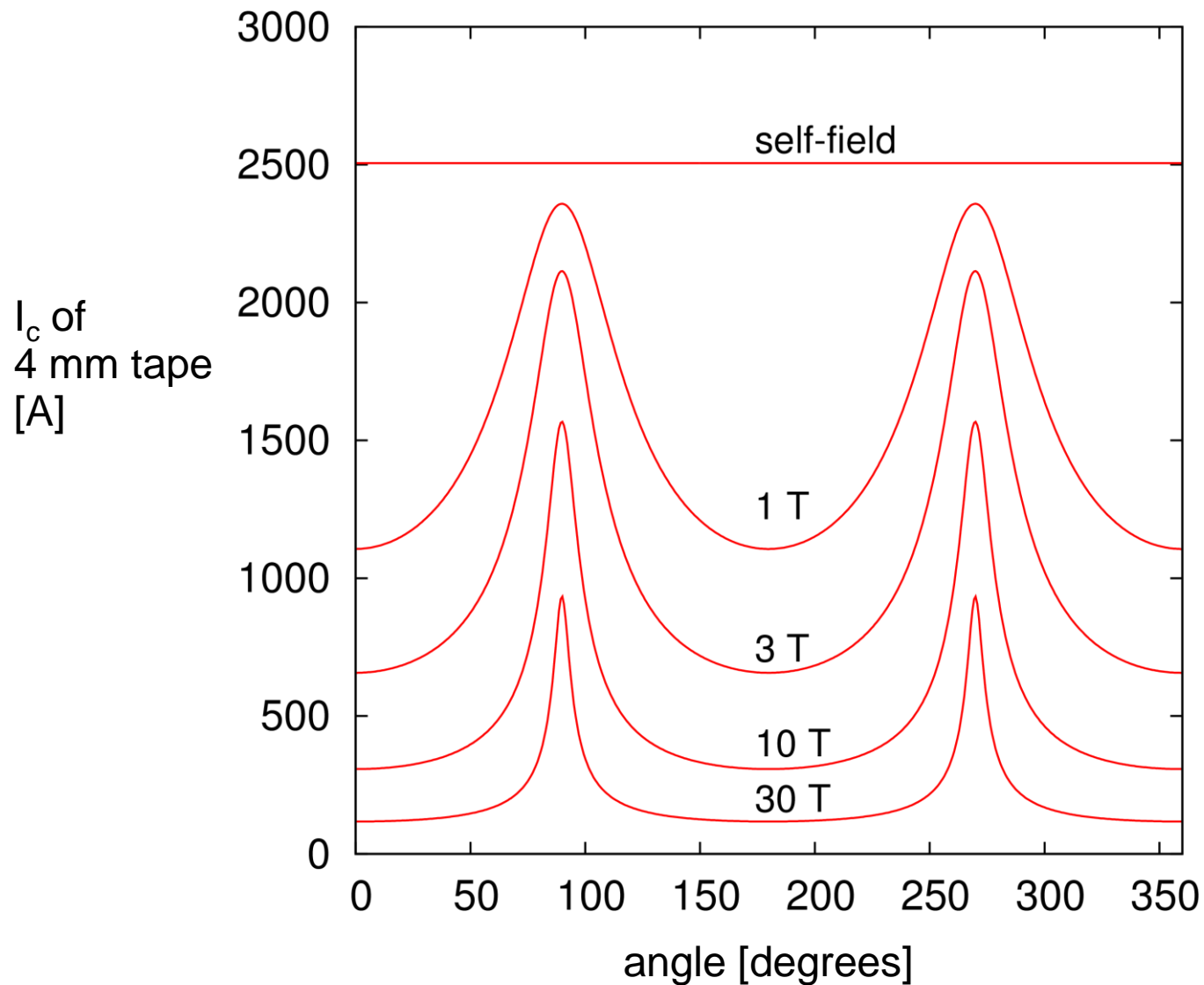
400 turns per pancake



more than 10000 turns



Anisotropic field dependent J_c

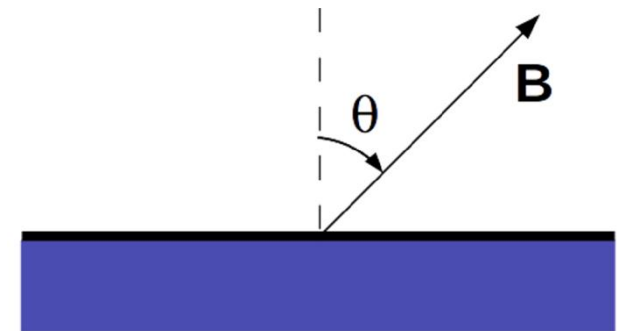


SuperPower tape

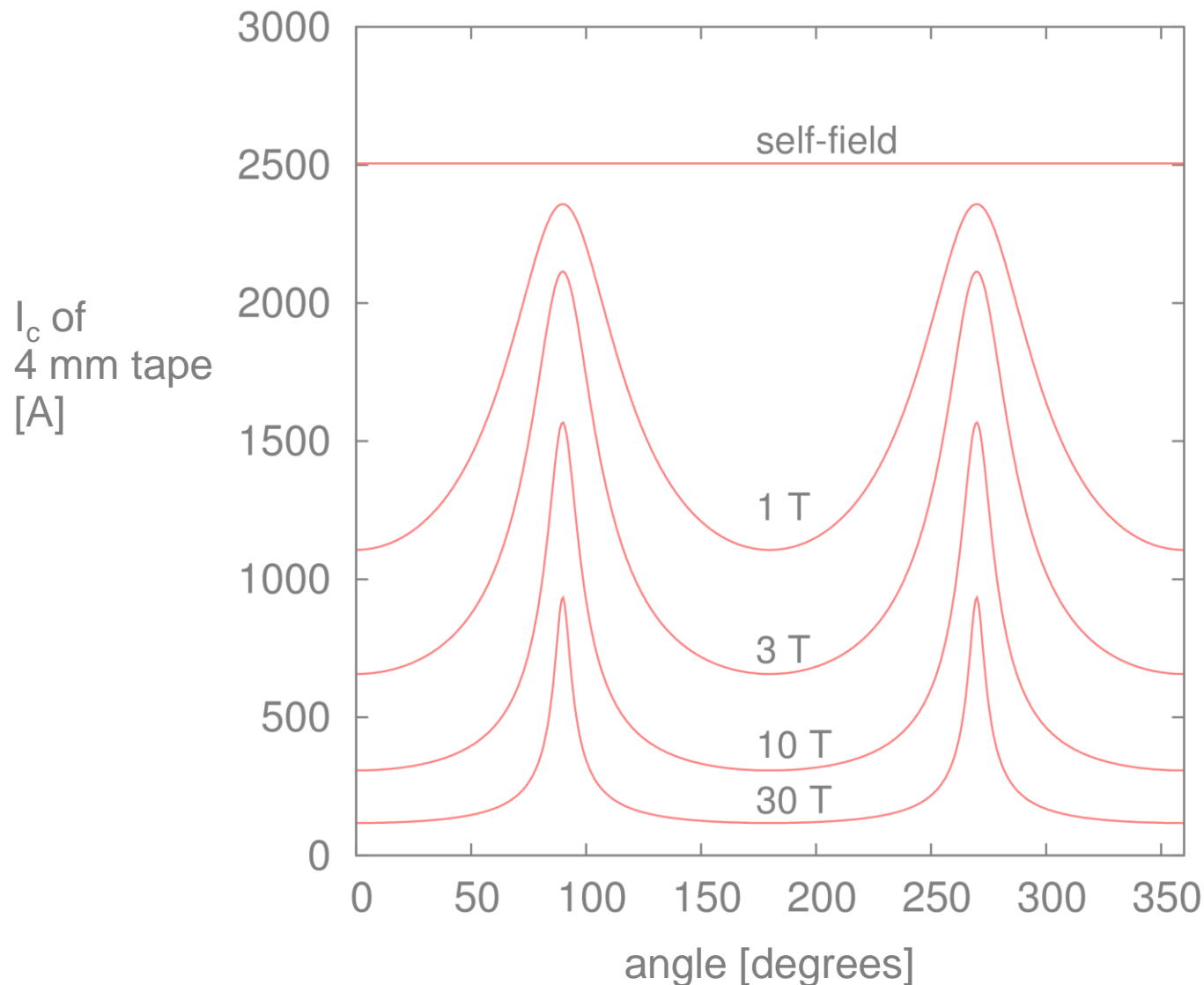
Fit of J_c from
measurements at **4.2 K**

D K Hilton et al. 2015 SuST

**Results useful for
high-field magnets**



Anisotropic field dependent J_c



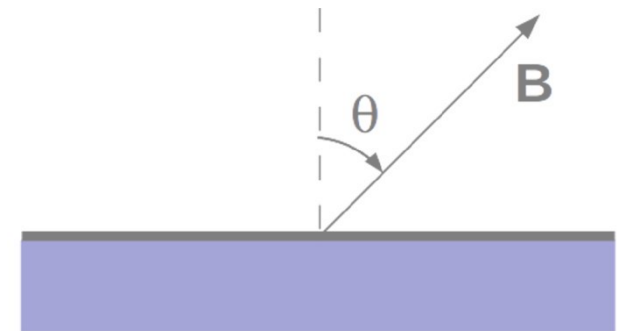
Power-law exponent: **30**

SuperPower tape

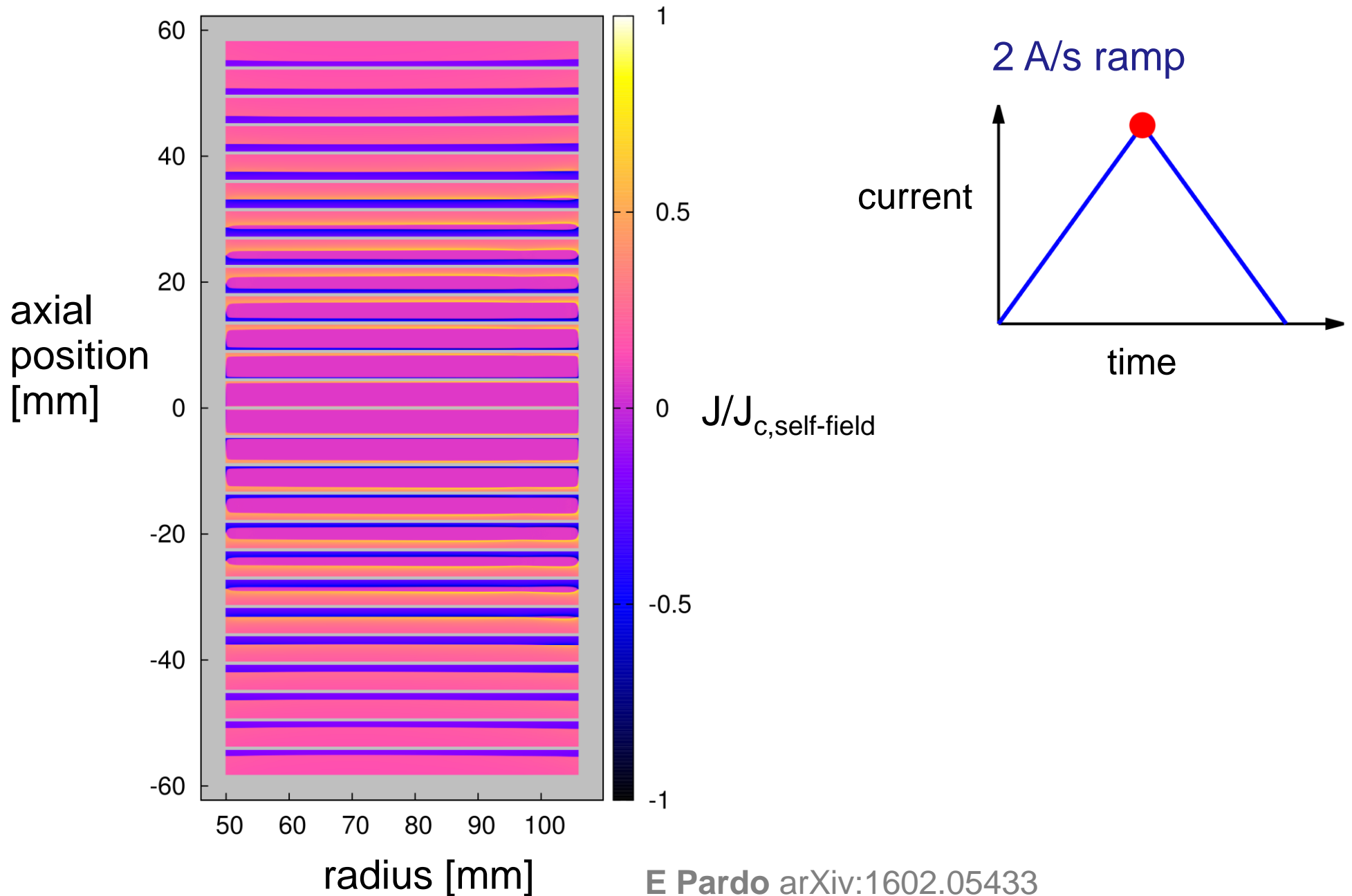
Fit of J_c from measurements at **4.2 K**

D K Hilton et al. 2015 SuST

Results useful for high-field magnets

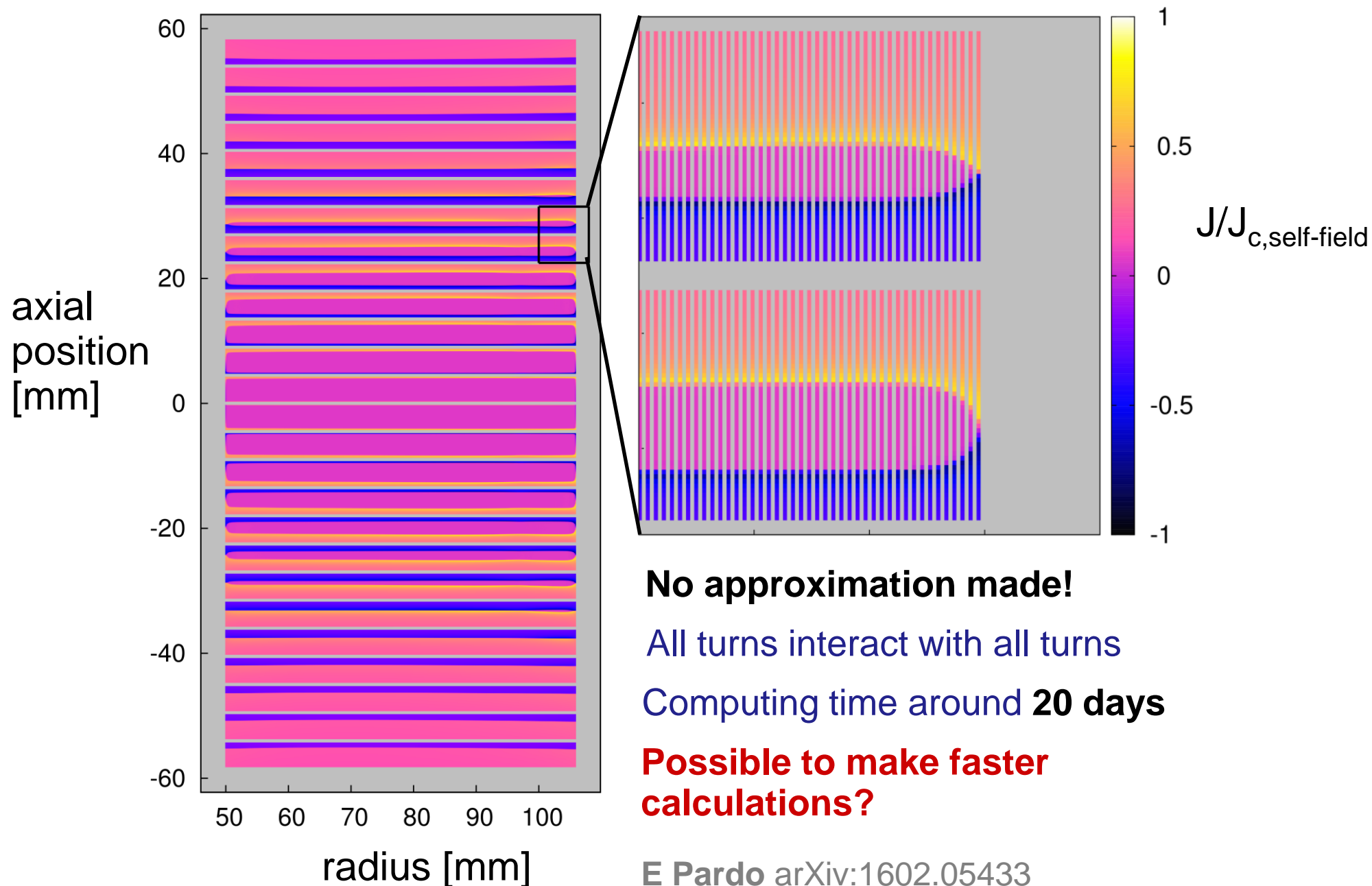


Important screening currents



E Pardo arXiv:1602.05433

Detailed current density at all turns



No approximation made!

All turns interact with all turns

Computing time around **20 days**

Possible to make faster calculations?

E Pardo arXiv:1602.05433

General variational principle

Power applications

Transformers

Magnets

- Real geometry
- **Continuous approximation**
- Screening current induced field

3D modelling

Non-linear magnetic materials

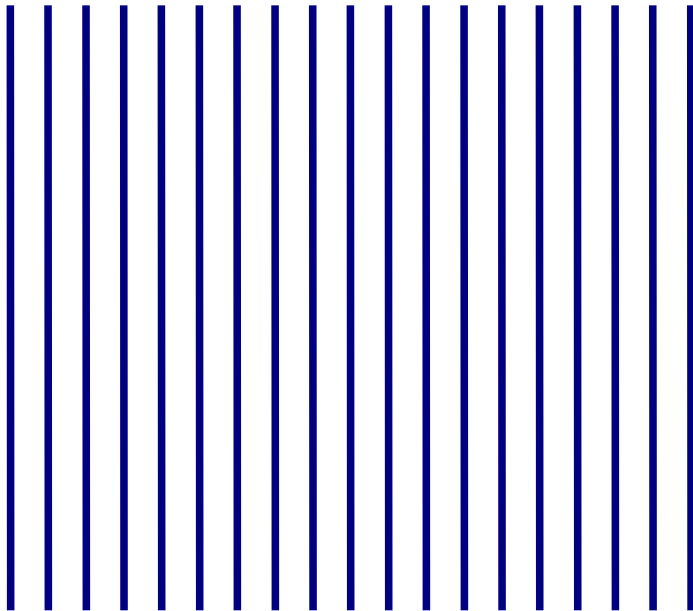
Continuous approximation

Pancake coil approximated by taking:

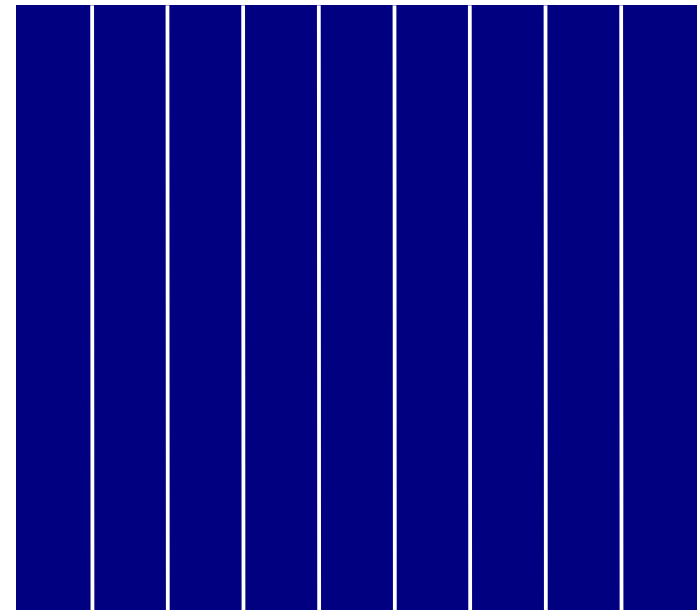
Less turns

No separation between turns

real coil

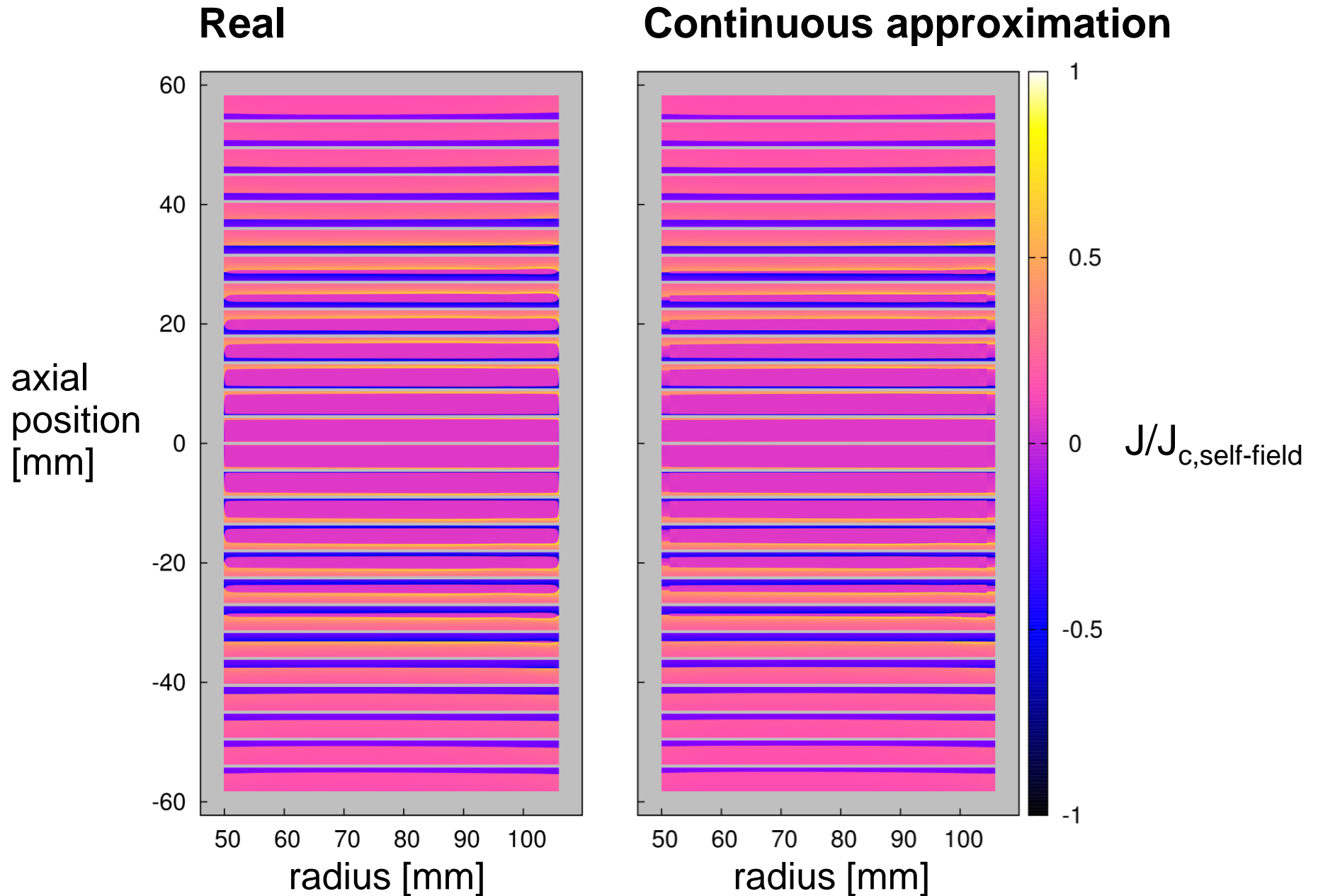


continuous approximation

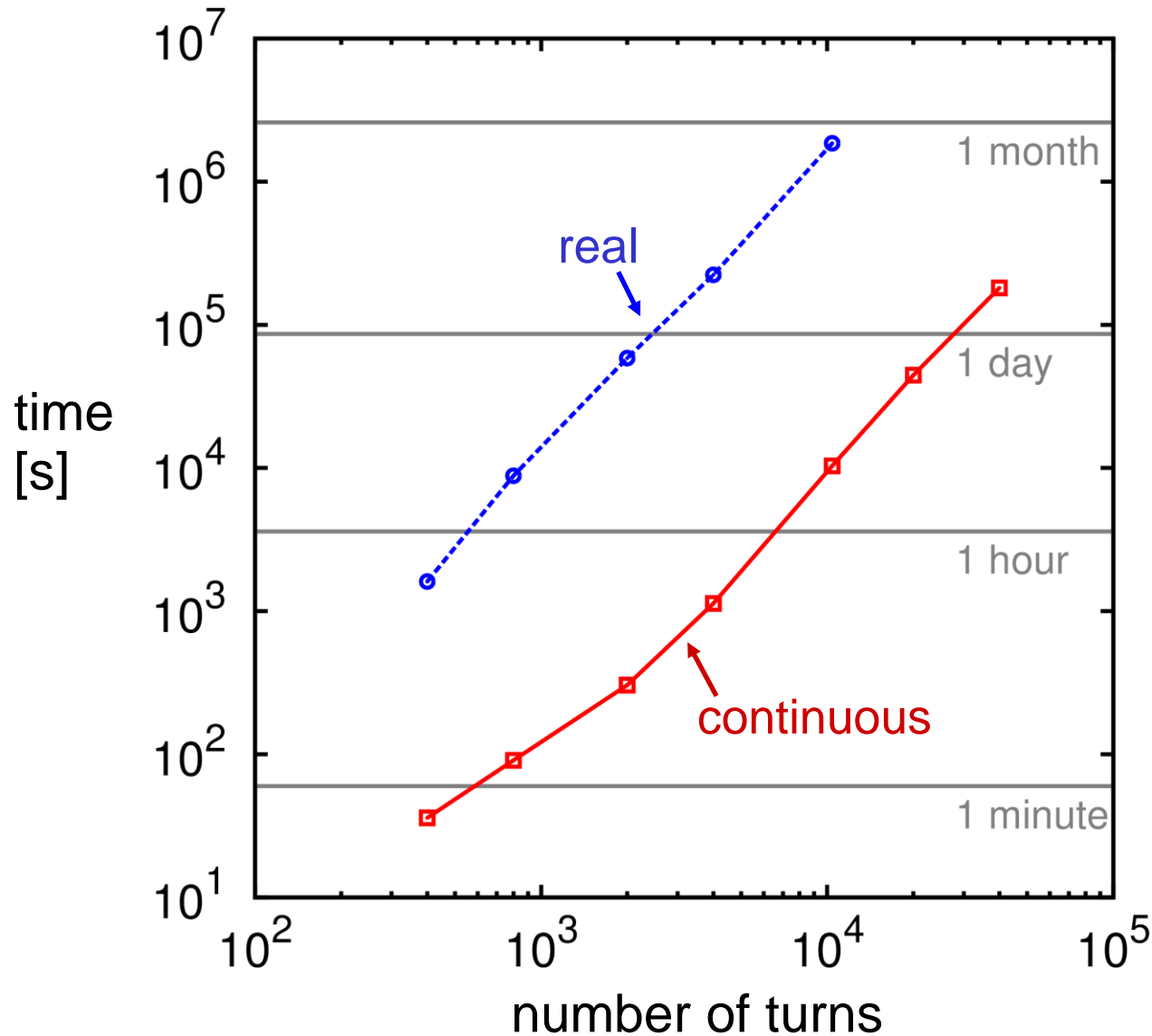


L Prigozhin, V Sokolovsky DOI: 10.1088/0953-2048/24/7/075012

Practically the same results **but faster!**



We computed up to 40000 turns



10000 turns: **2.7 hours**

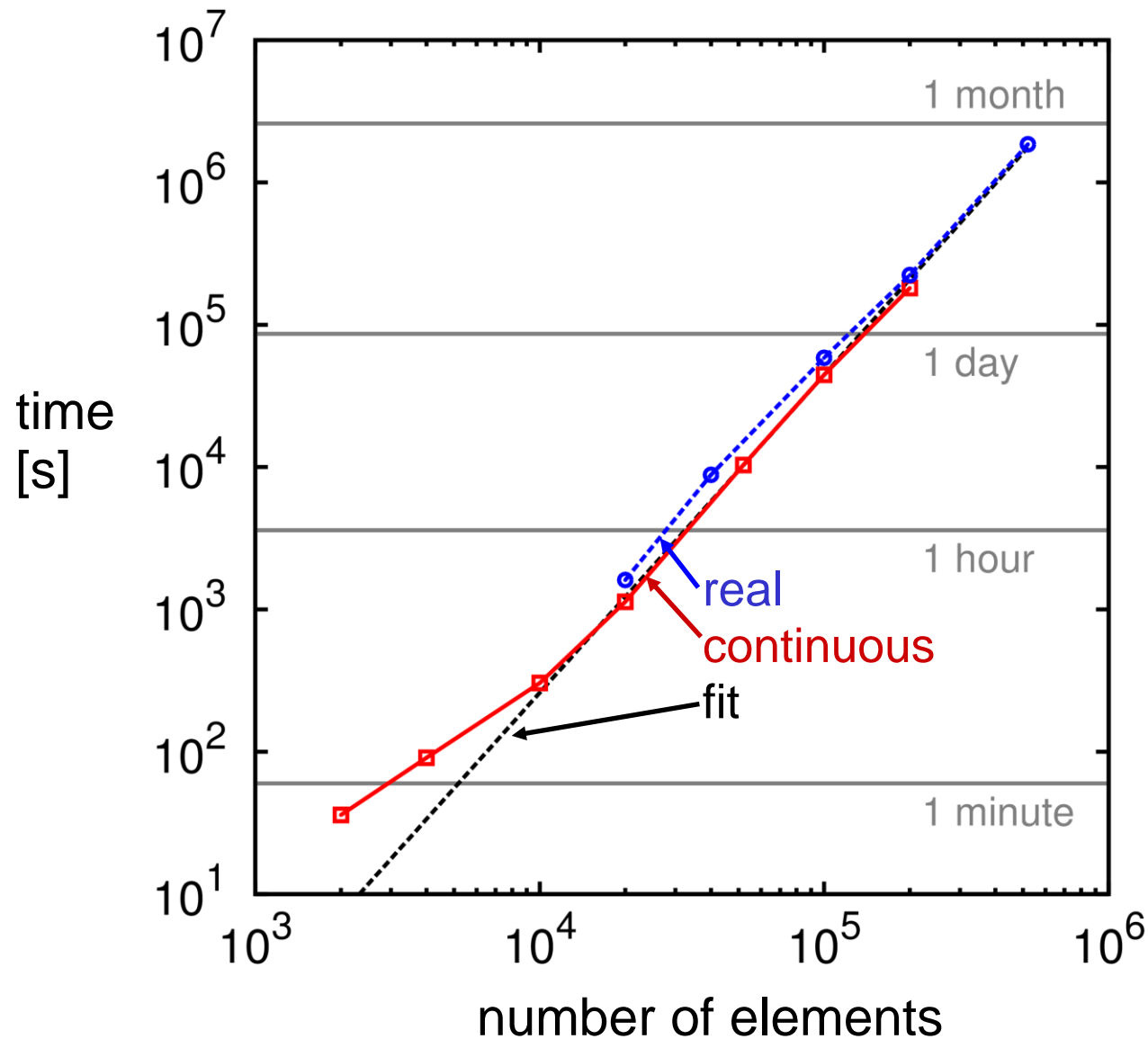
40000 turns: **2 days**

fulfills requirements for high-field magnets

H W Weijers et al. 2014
IEEE TAS

S Awaji et al. 2014 IEEE TAS

Up to 500 000 elements in the superconductor



**Computing time
scales as second power**

General variational principle

Power applications

Transformers

Magnets

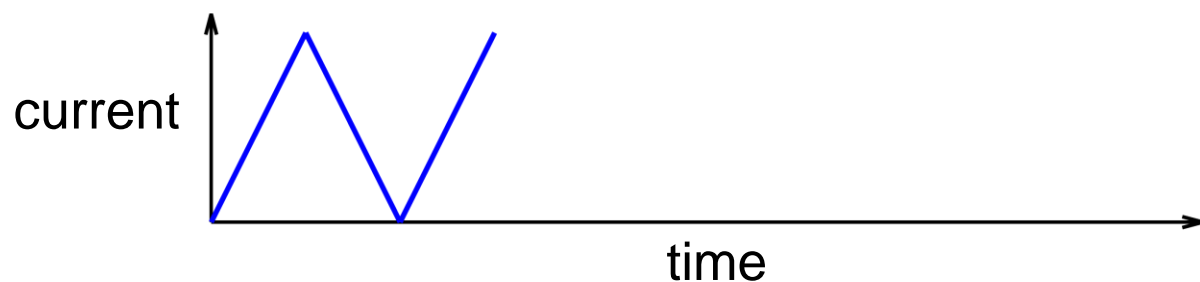
- Real geometry
- Continuous approximation
- Screening current induced field

3D modelling

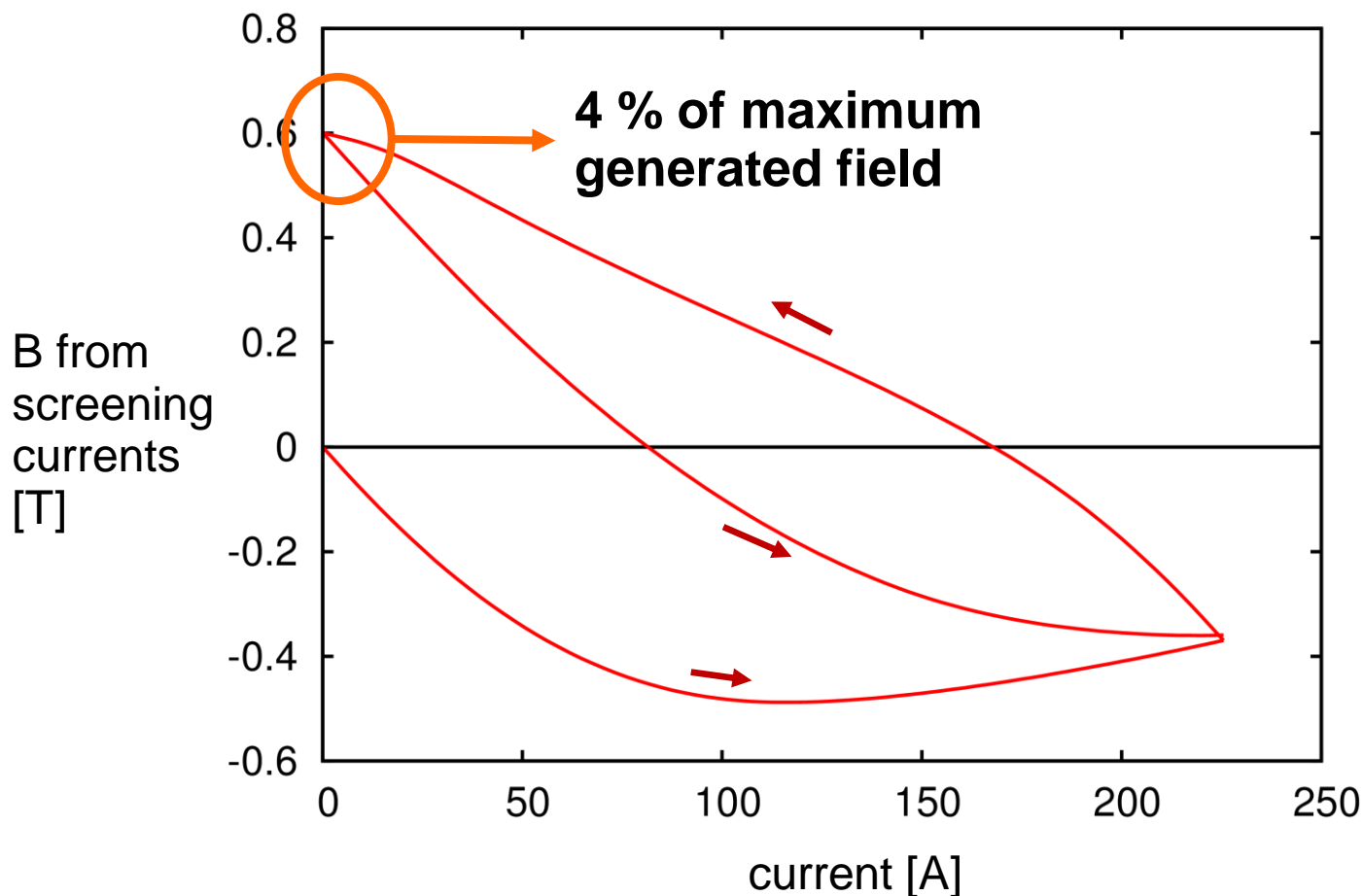
Non-linear magnetic materials

Screening currents are important

E Pardo arXiv:1602.05433

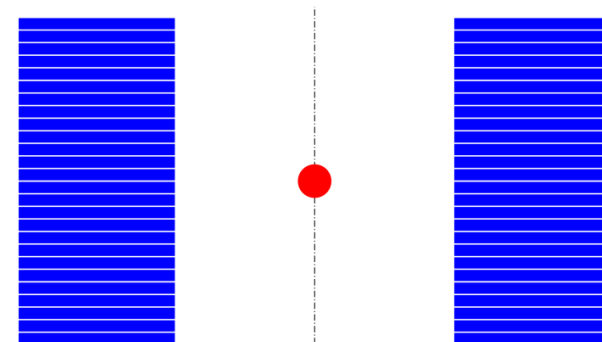


generated field
at maximum current **15 T**



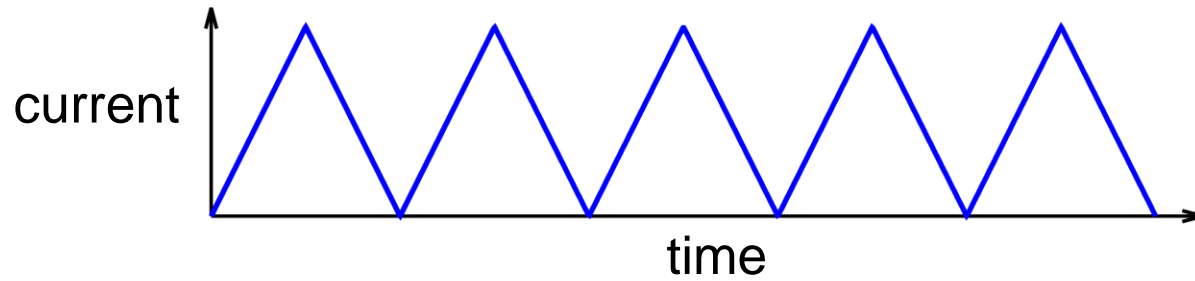
**Important for
MRI and NMR**

magnetic field
at bore center

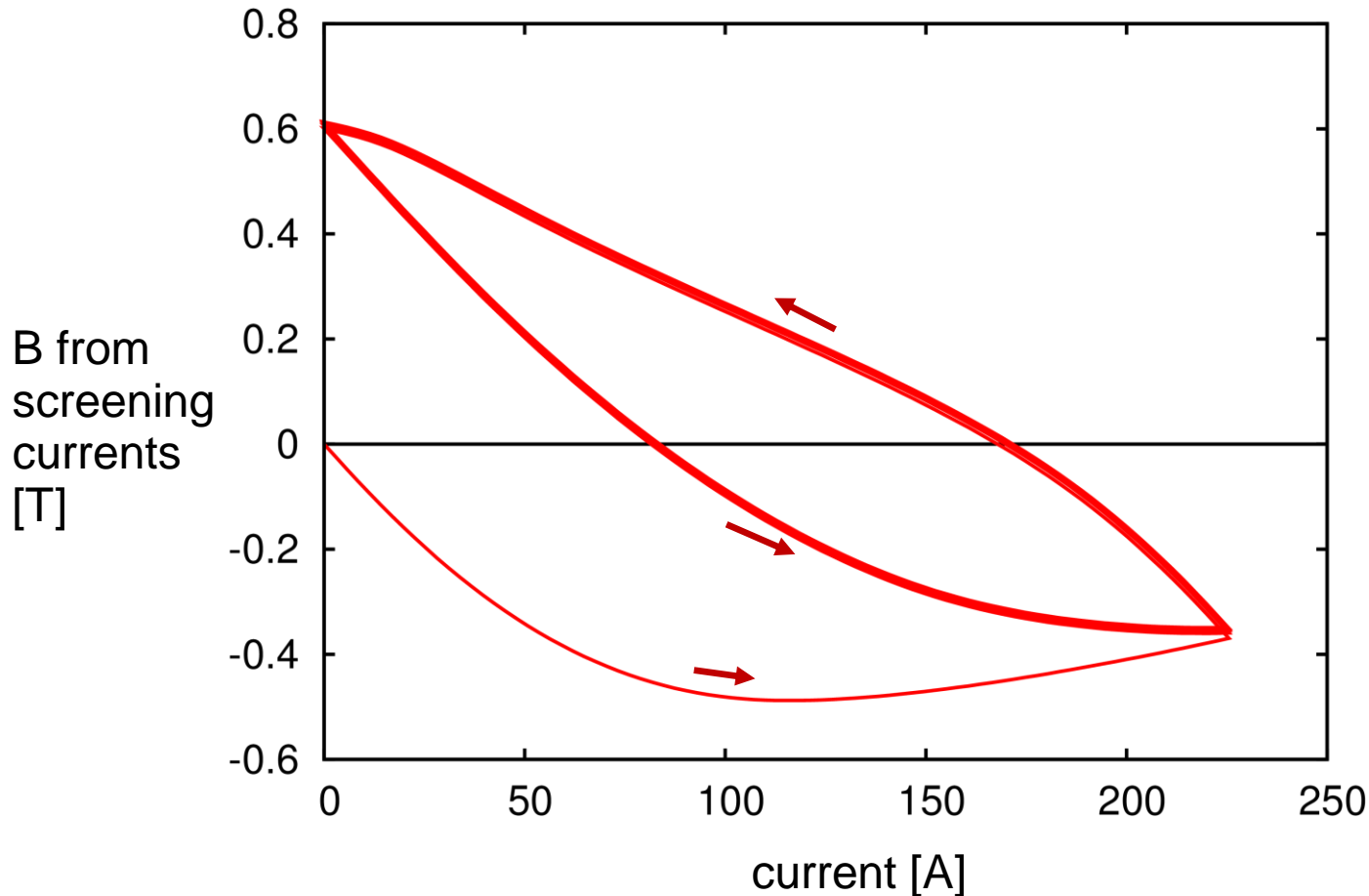


Screening currents are important

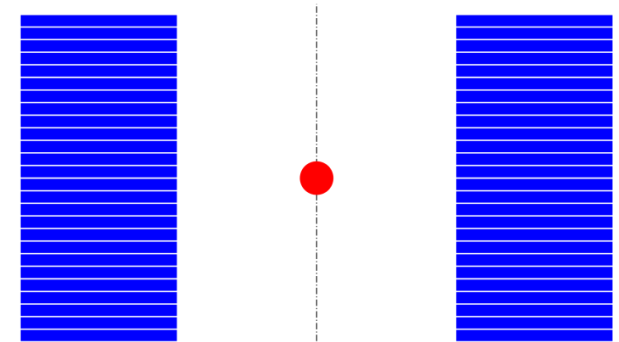
E Pardo arXiv:1602.05433



**Stationary state
after several cycles**



magnetic field
at bore center



**The variational method is efficient
for large number of elements**

Promising for 3D modelling

General variational principle

Power applications

3D modelling

Non-linear magnetic materials

General variational principle

Power applications

3D modelling

Novel variational principle

Force-free effects in films

3D bulk

Non-linear magnetic materials

Novel 3D variational principle

M Kapolka, E Pardo arXiv:1605.09610

$$\mathbf{J} = \nabla \times \mathbf{T} \rightarrow \text{current potential}$$

\mathbf{T} is the minimization variable

$$L = \int_V dV \left[\frac{1}{2} \Delta \mathbf{J} \cdot \frac{\Delta \mathbf{A}_J}{\Delta t} + \Delta \mathbf{J} \cdot \frac{\Delta \mathbf{A}_a}{\Delta t} + U(\mathbf{J}) \right]$$

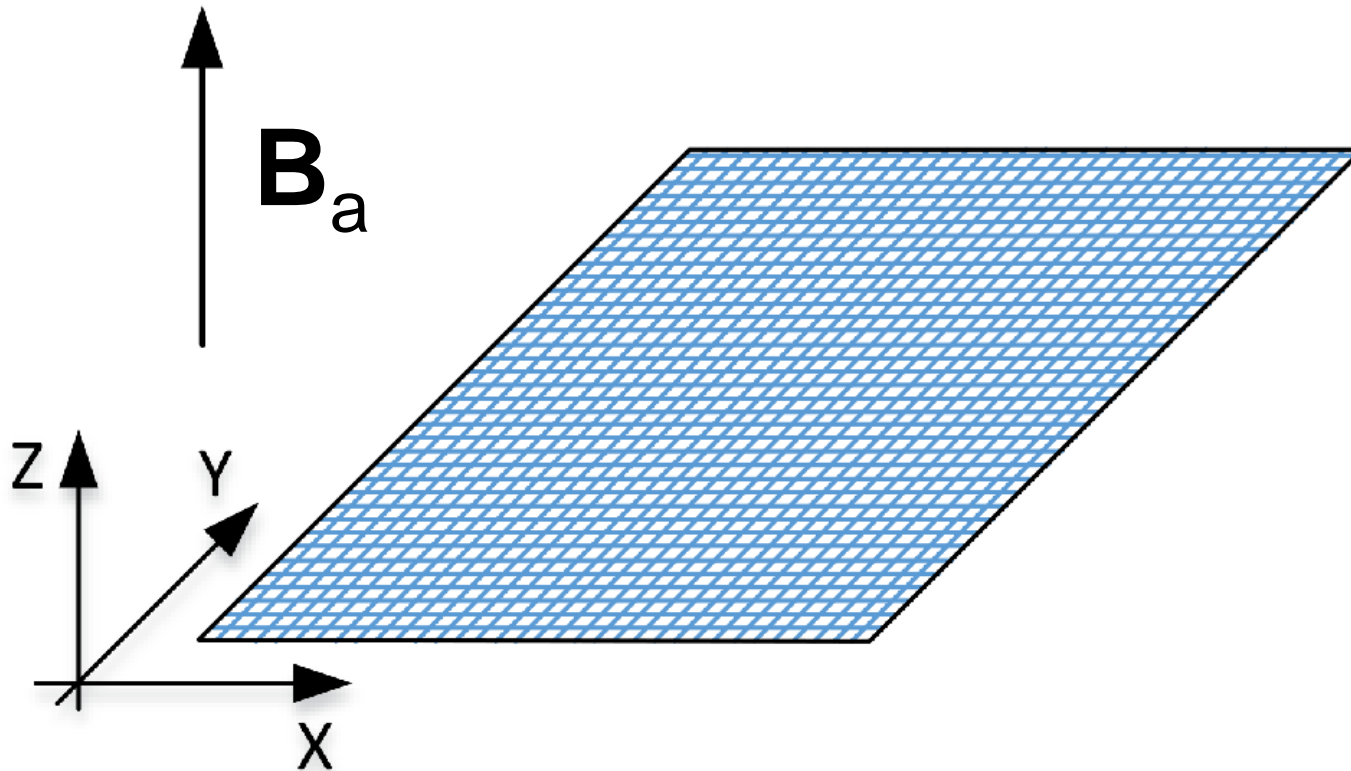
or

$$L = \int_V dV \left[\frac{1}{2} \Delta \mathbf{T} \cdot \frac{\Delta \mathbf{B}_J}{\Delta t} + \Delta \mathbf{T} \cdot \frac{\Delta \mathbf{B}_a}{\Delta t} + U(\nabla \times \mathbf{T}) \right]$$

You can forget about scalar potential!

Still easy to take transport currents into account

Thin surface

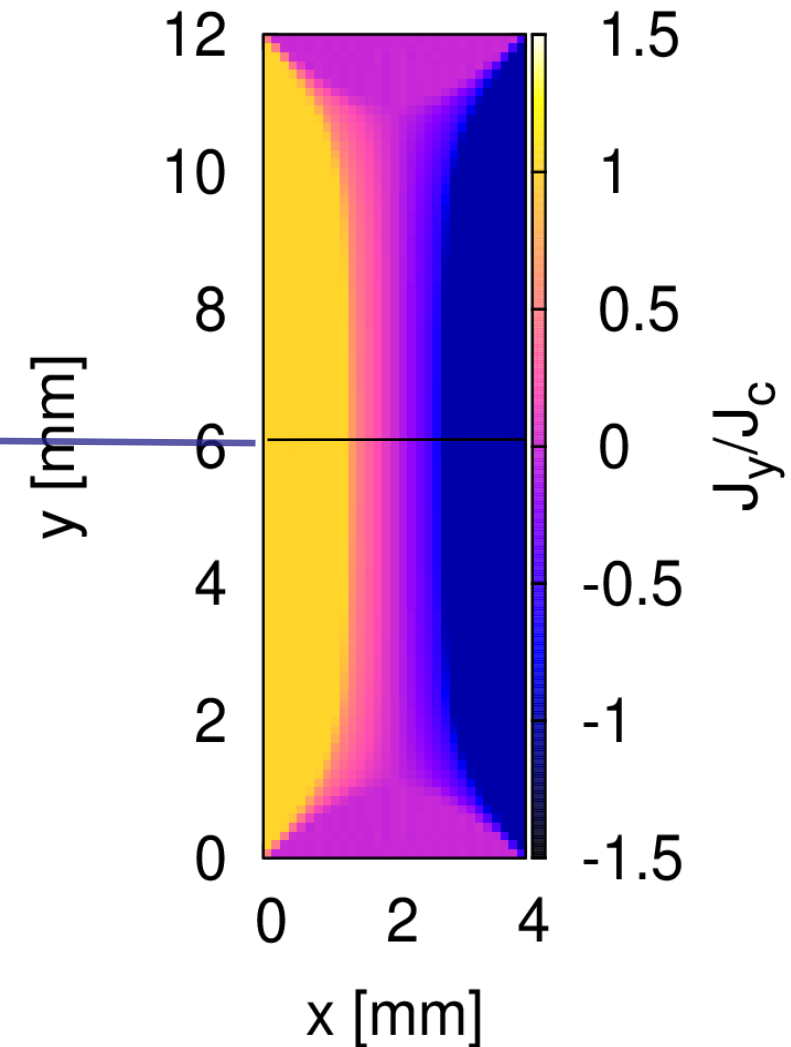
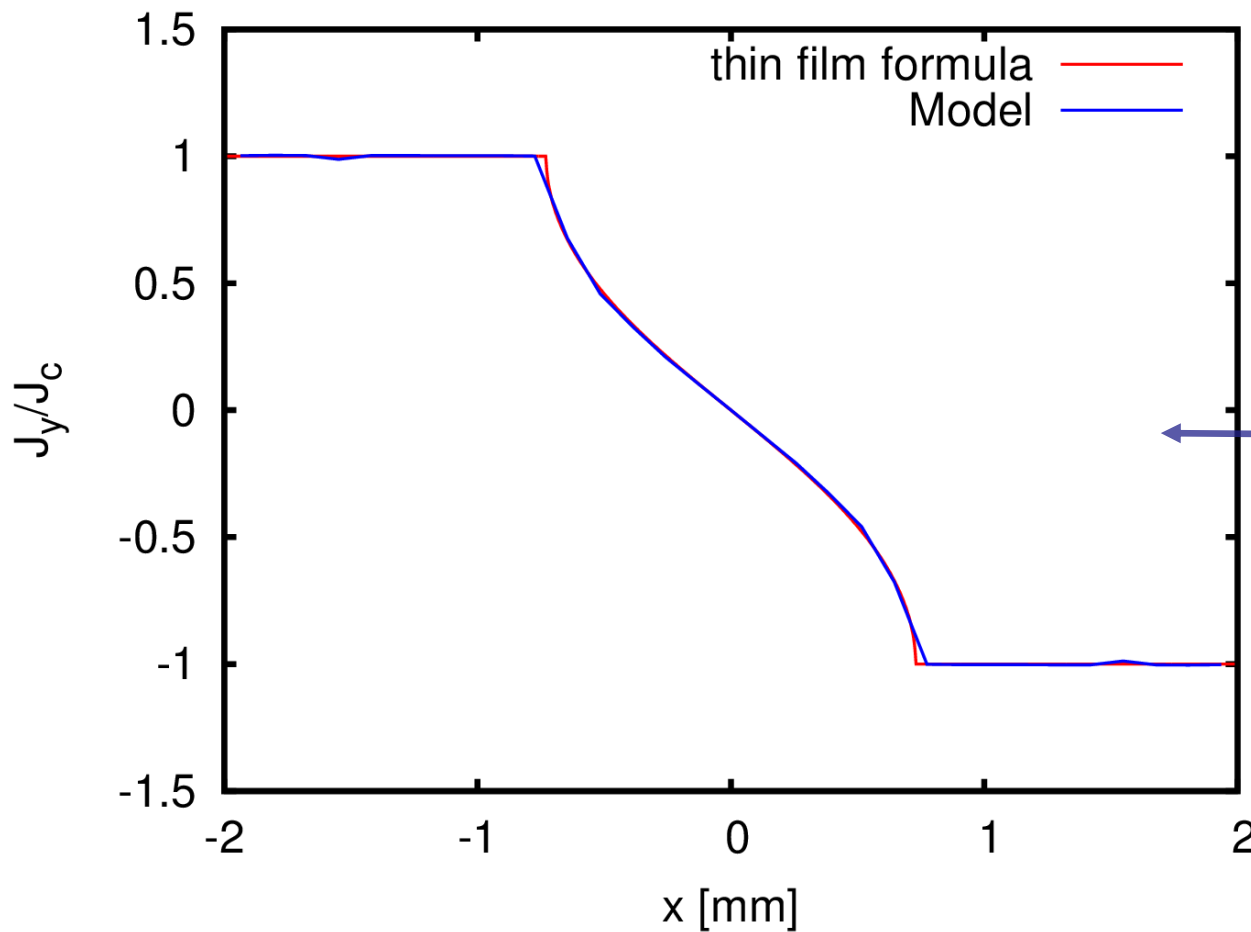


Model agrees with thin film formula

Power-law exponent **1000**

Tape midplane

Applied field: **20 mT**



General variational principle

Power applications

3D modelling

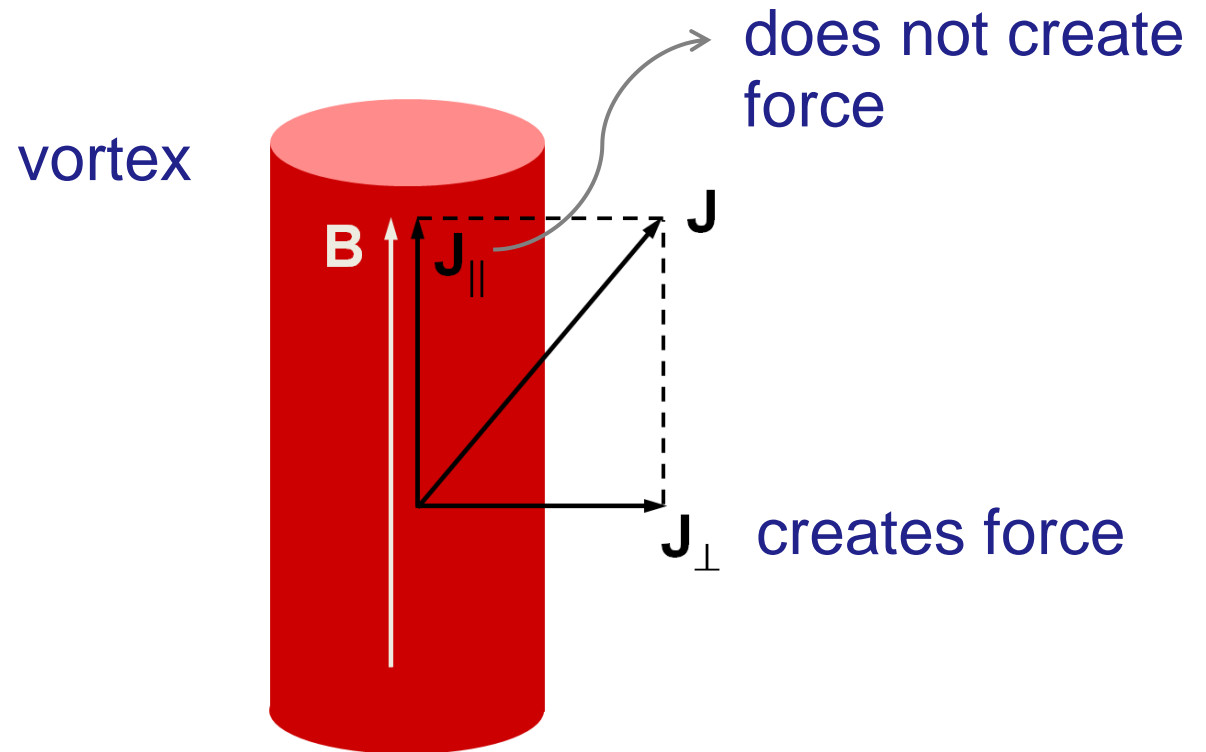
Novel variational principle

Force-free effects in films

3D bulk

Non-linear magnetic materials

Flux-free effects cause anisotropic $E(\mathbf{J})$



Two critical currents:

$\mathbf{J}_{c\perp}$

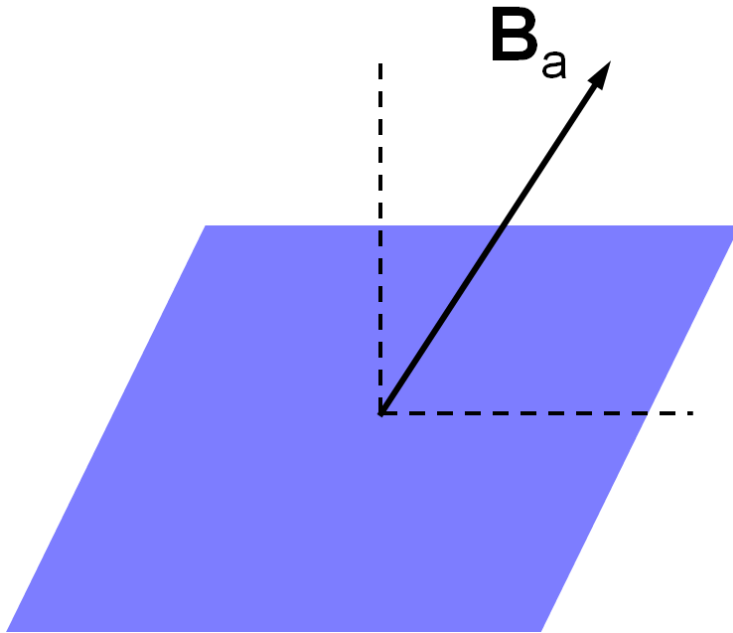
$\mathbf{J}_{c\parallel}$

Anisotropic power law:

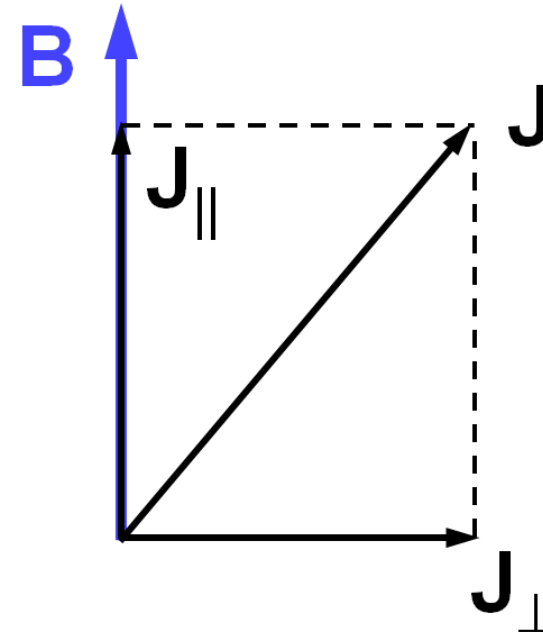
$$\mathbf{E}(\mathbf{J}) = E_c \left[\frac{J_{\parallel}^2}{J_{c\parallel}^2} + \frac{J_{\perp}^2}{J_{c\perp}^2} \right]^{\frac{n-1}{2}} \cdot \left(\frac{J_{\parallel}}{J_{c\parallel}} \frac{J_{\perp}}{J_{c\parallel}} \mathbf{e}_{\parallel} + \frac{J_{\perp}}{J_{c\perp}} \mathbf{e}_{\perp} \right)$$

A Badia, C Lopez DOI: 10.1088/0953-2048/28/2/024003

Flux-free effects in thin films



There is a force-free
component



$$J_{c\parallel} = 3J_{c\perp}$$

Force-free J_c

Usual depinning J_c

Mishev et al.

DOI: 10.1088/0953-2048/28/10/102001

General variational principle

Power applications

3D modelling

Novel variational principle

Force-free effects in films

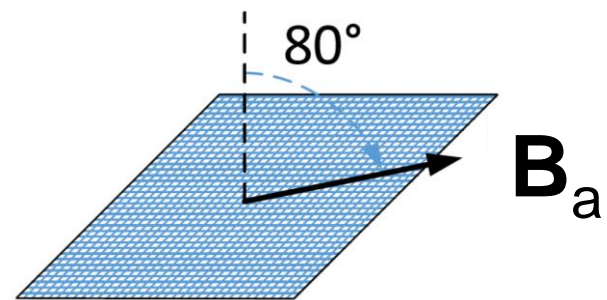
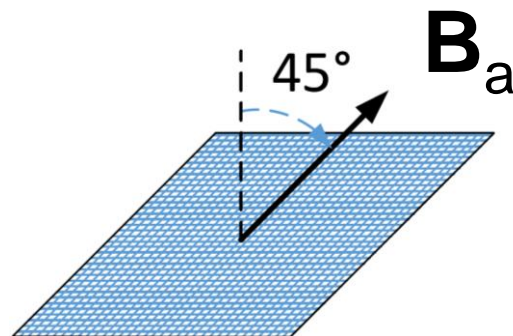
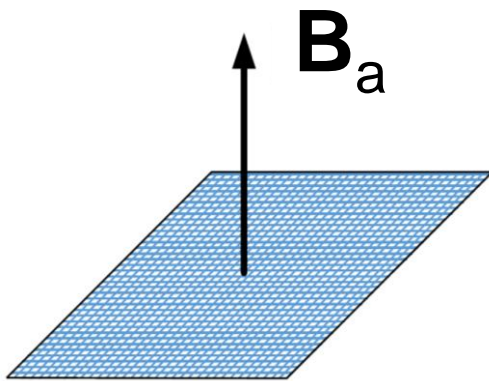
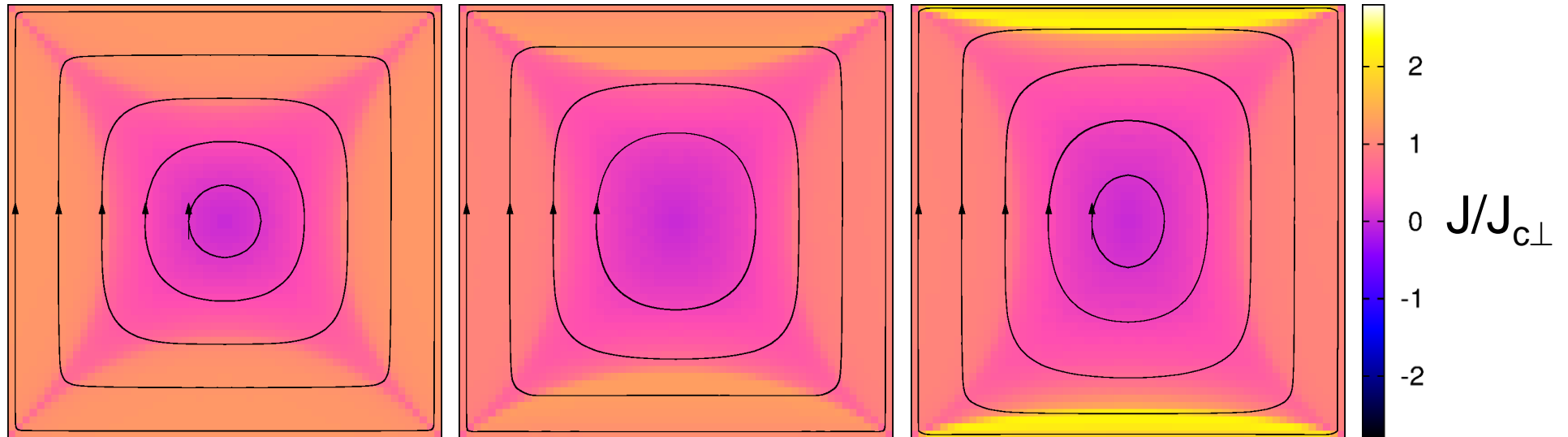
3D bulk

Non-linear magnetic materials

Flux-free effect increases J_c

Perpendicular field component: **23 mT**

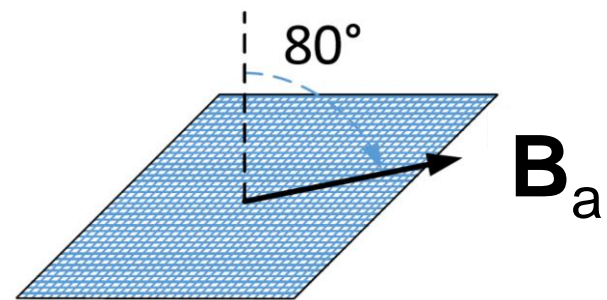
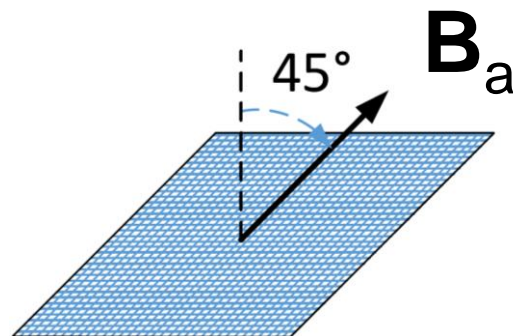
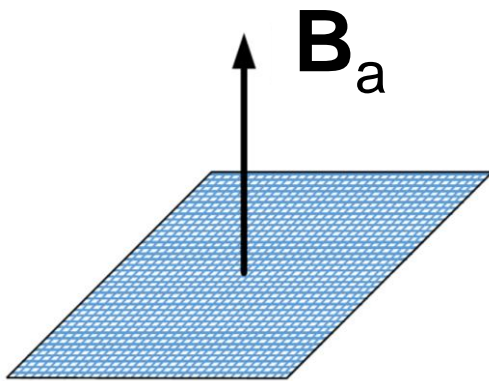
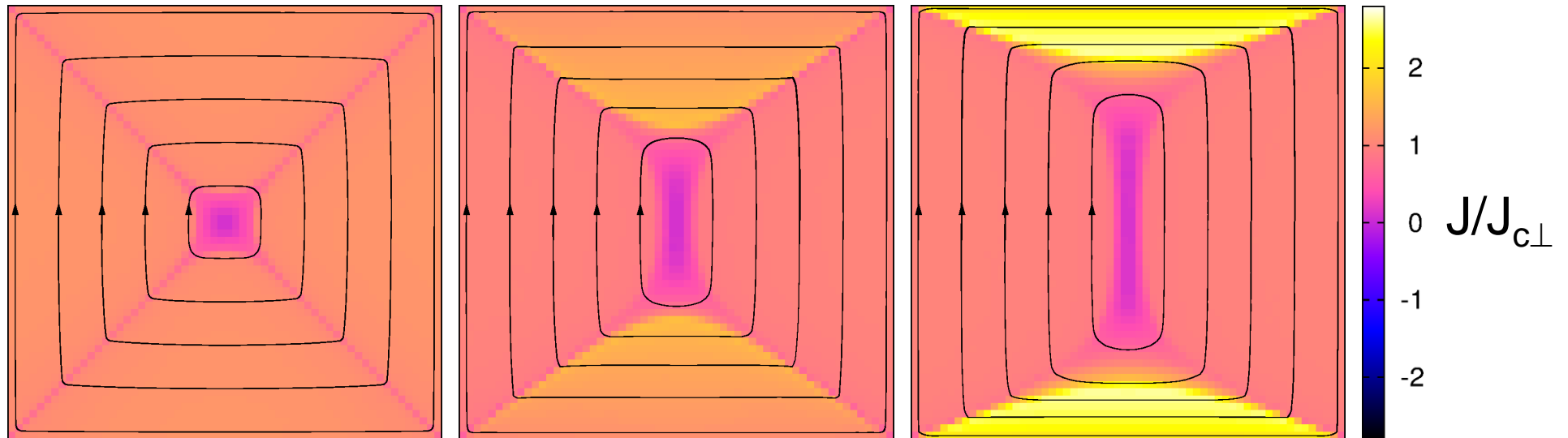
Film **top view**



Asymmetric current saturation

Perpendicular field component: **50 mT**

Film **top view**



General variational principle

Power applications

3D modelling

Novel variational principle

Force-free effects in films

3D bulk

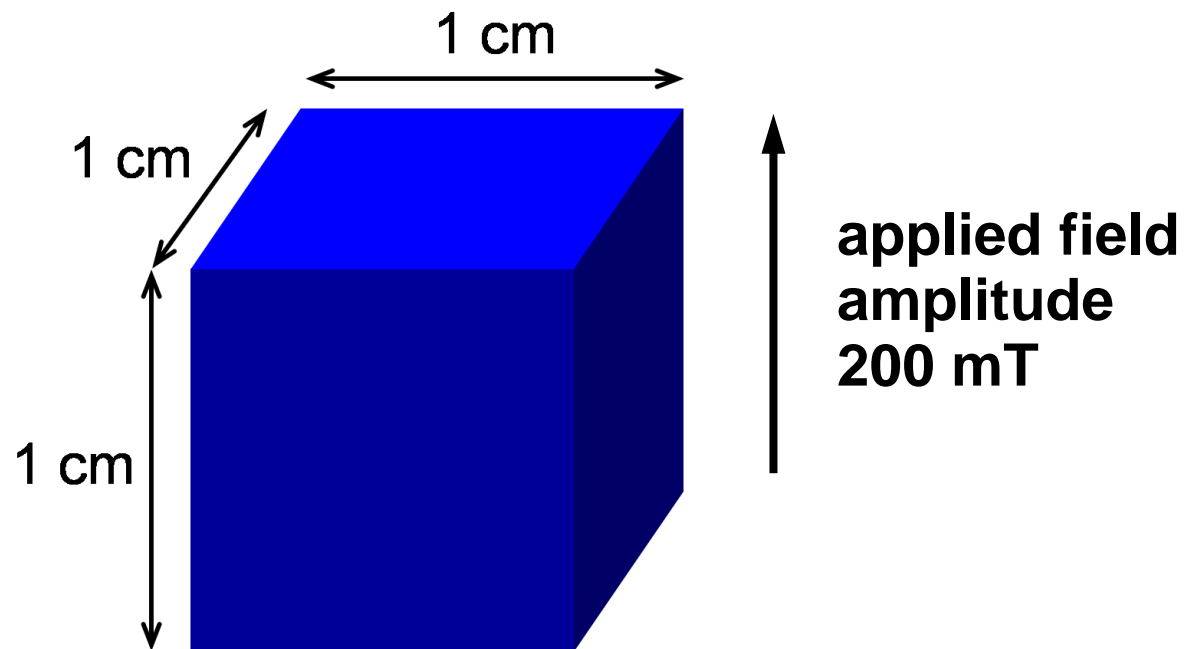
Non-linear magnetic materials

3D bulk

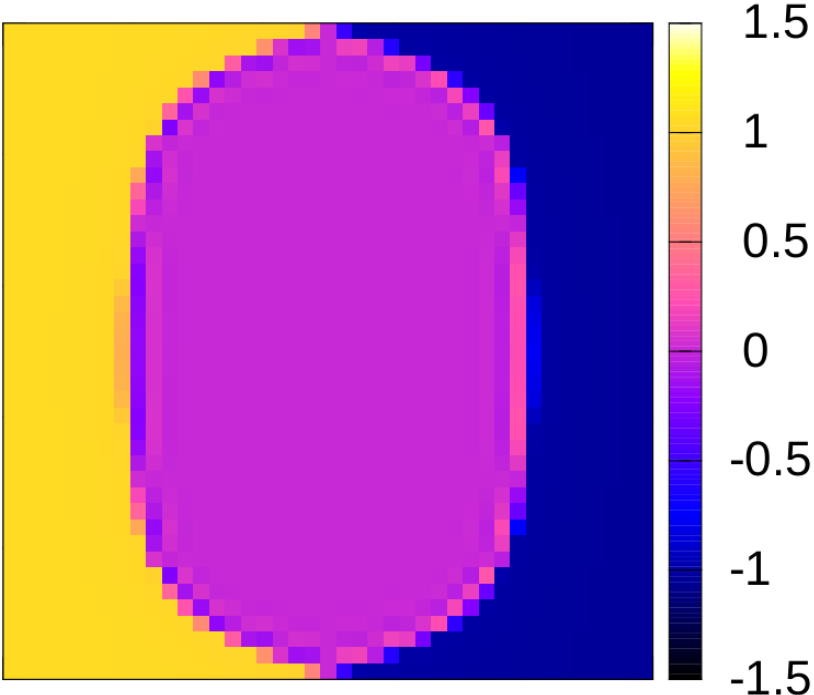
Frequency: **50 Hz** sinusoidal

Power-law exponent: **100**

$J_c = 10^8 \text{ A/m}^2$

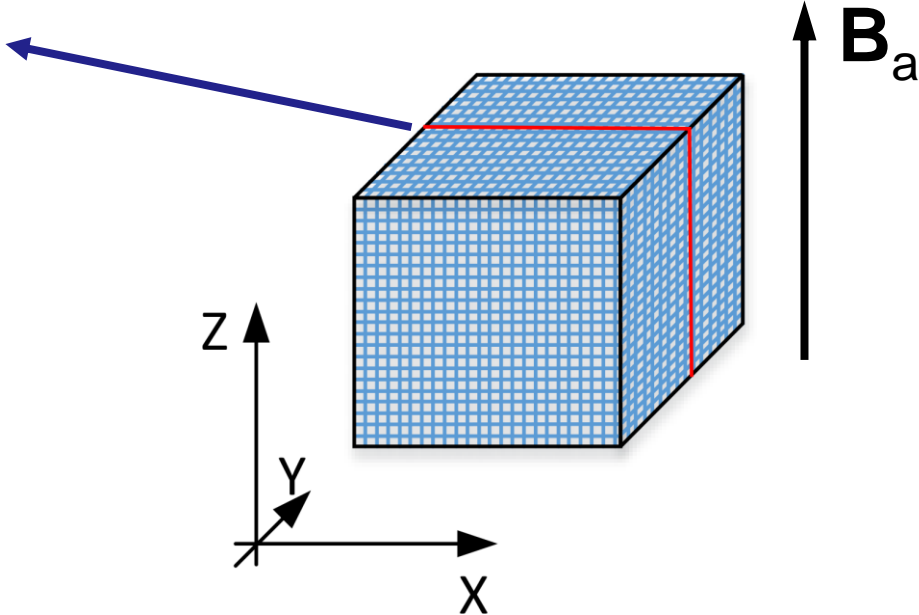


Good resolution for 3D

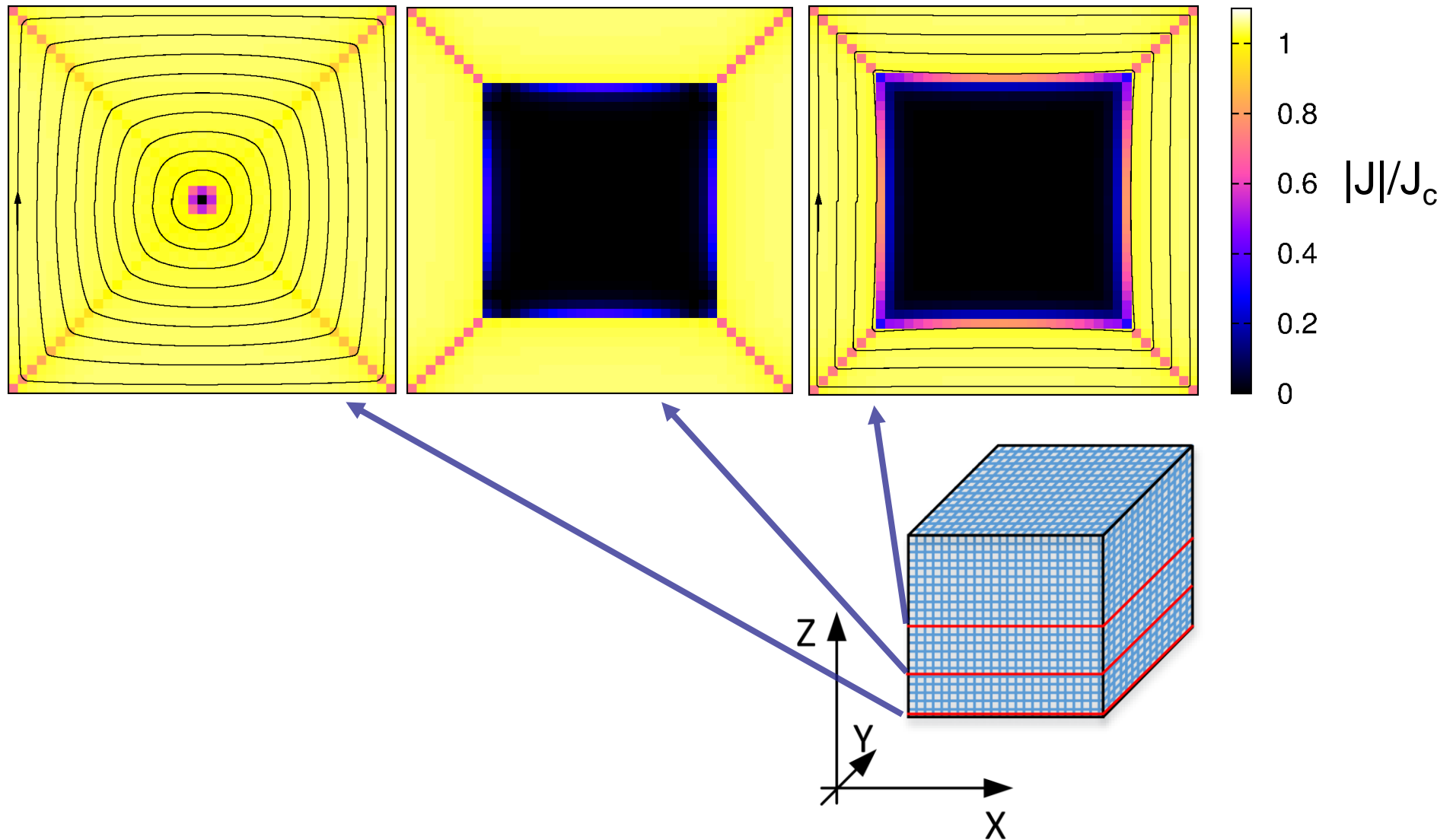


more than **210 000** degrees of freedom in the superconductor

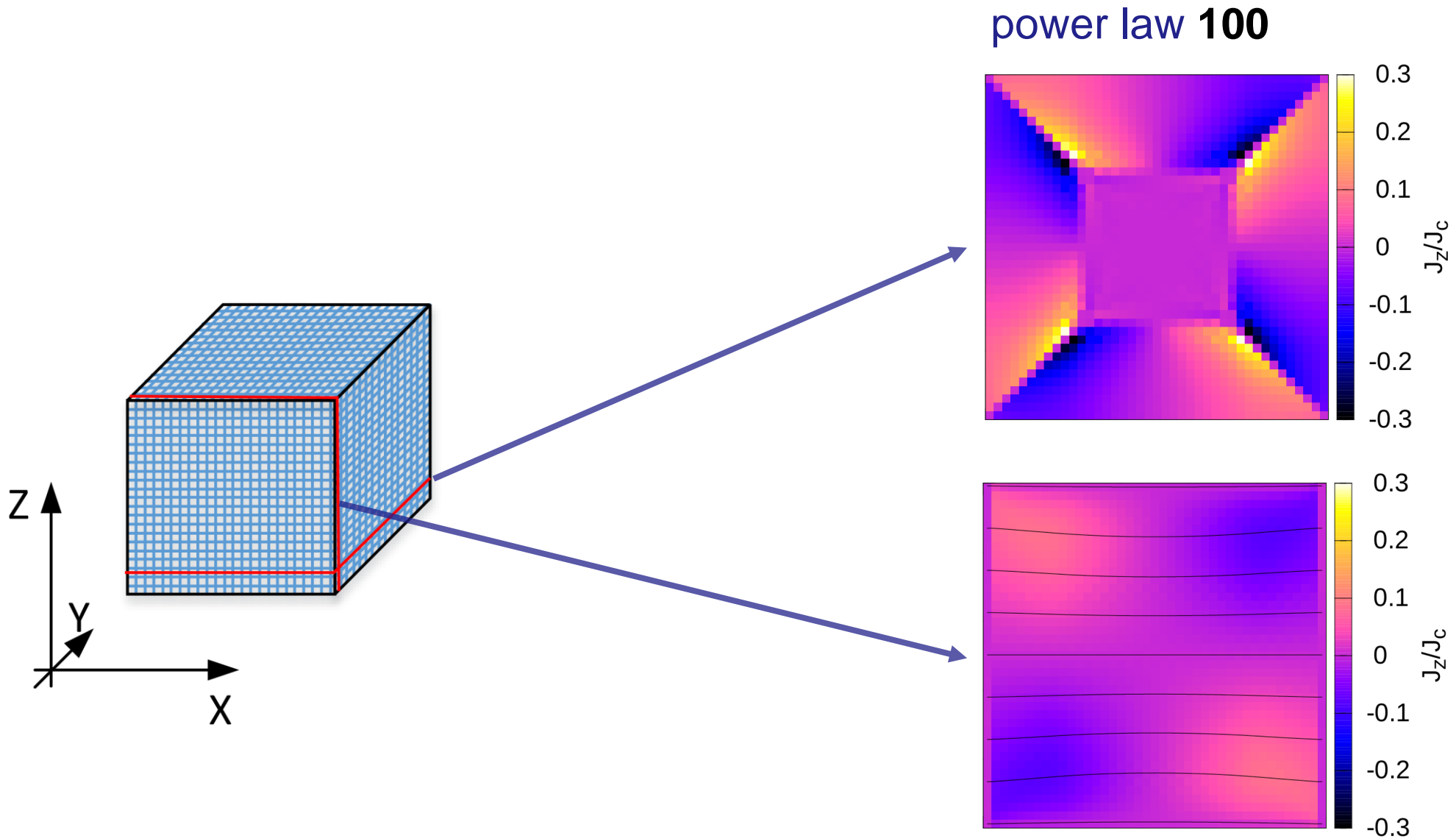
no symmetries taken into account yet



3D current flow

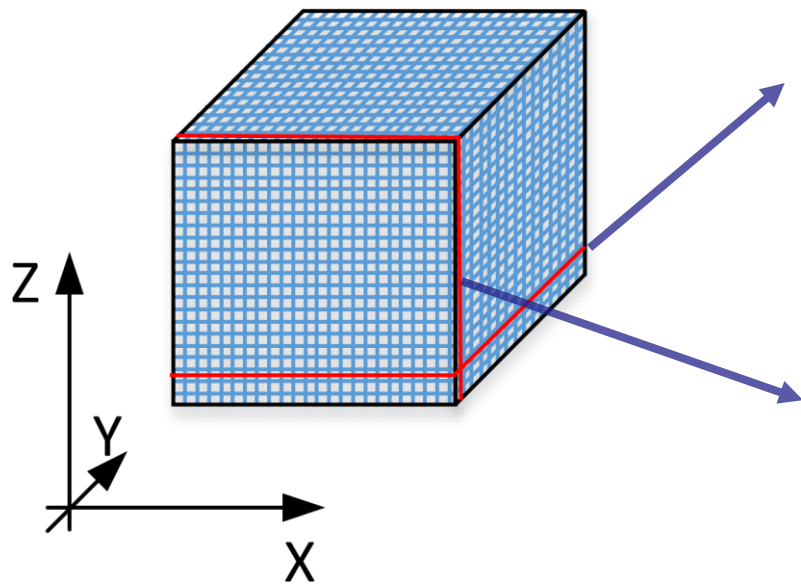


Vertical component is important

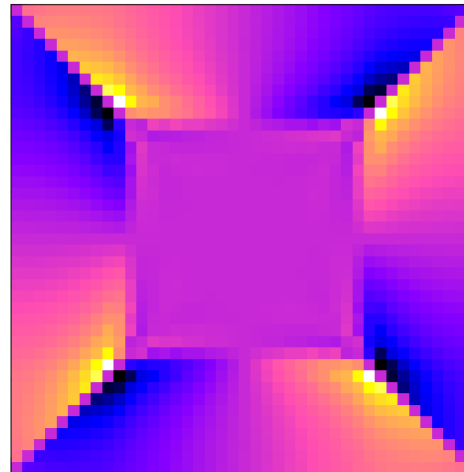


Vertical component is important

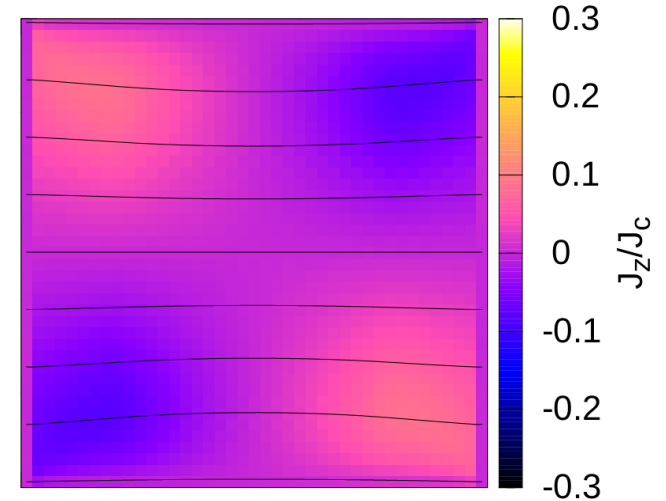
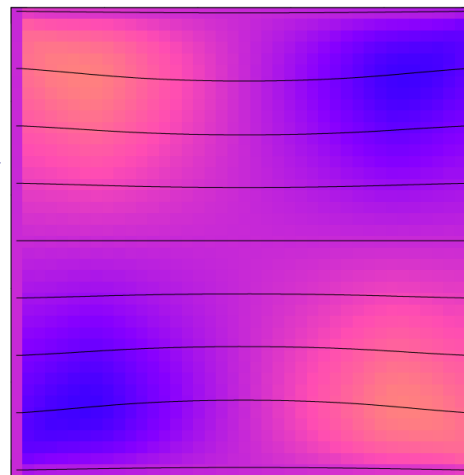
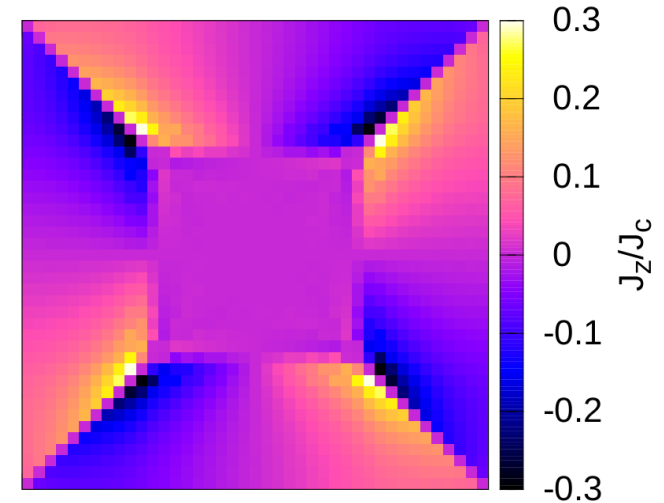
Smooth $E(J)$ relation cannot be the cause



power law 30



power law 100



3D variational principle for the magnetic material

Reversible non-linear materials

Equation

$$\mathbf{B}(\mathbf{M}) = \mathbf{B}_M + \mathbf{B}_a + \mathbf{B}_J$$

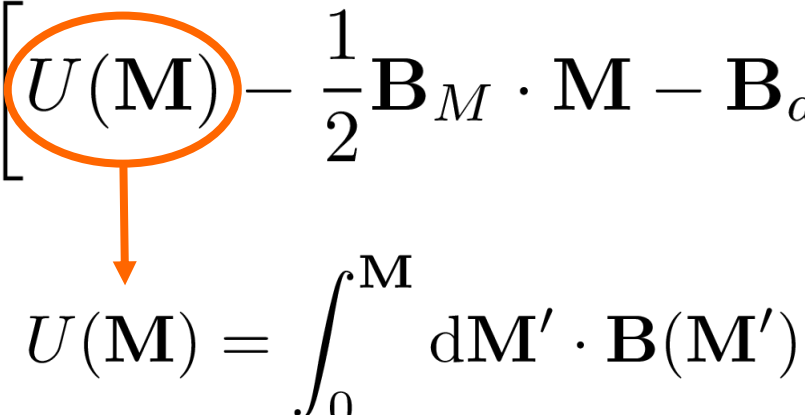
\mathbf{B} created by $\nabla \times \mathbf{M}$ \mathbf{B} from currents

non-linear relation applied \mathbf{B}

is the Euler-Lagrange equation of

$$L_M = \int_V dV \left[U(\mathbf{M}) - \frac{1}{2} \mathbf{B}_M \cdot \mathbf{M} - \mathbf{B}_a \cdot \mathbf{M} - \mathbf{B}_J \cdot \mathbf{M} \right]$$
$$U(\mathbf{M}) = \int_0^{\mathbf{M}} d\mathbf{M}' \cdot \mathbf{B}(\mathbf{M}')$$

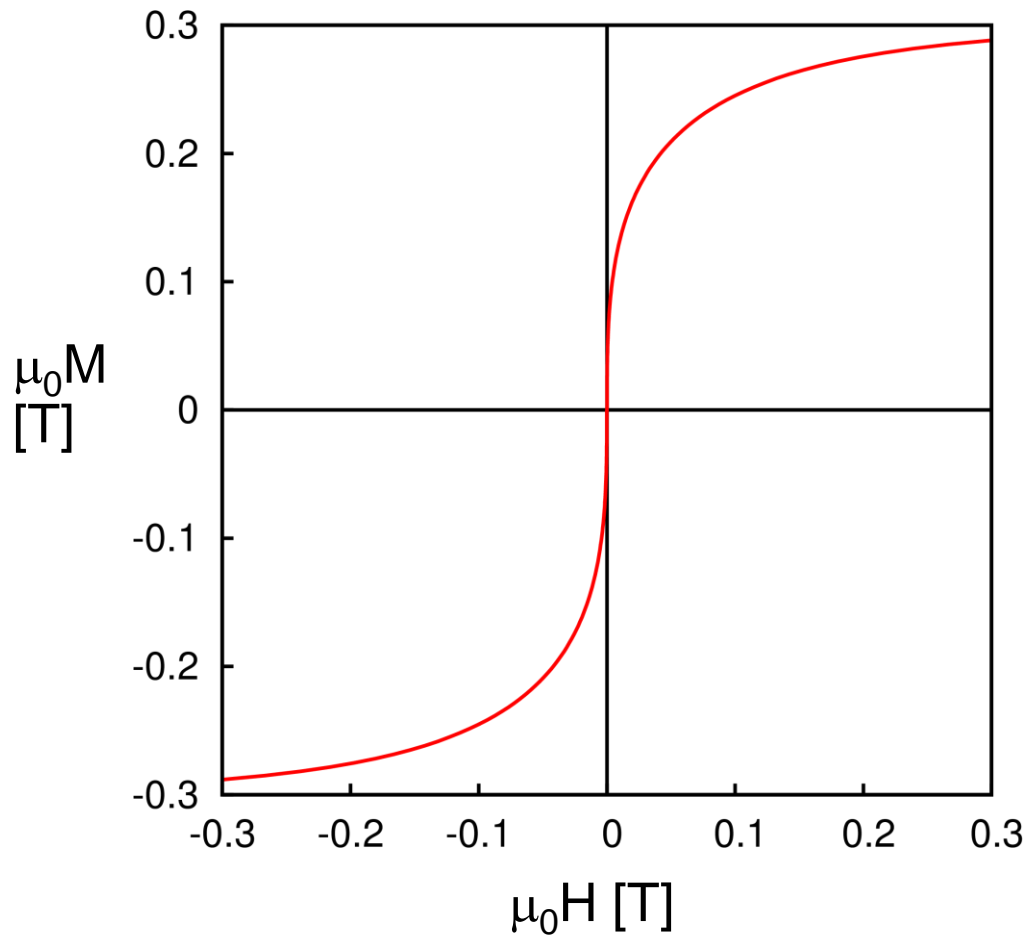
3D variational principle for the magnetic material

$$L_M = \int_V dV \left[U(\mathbf{M}) - \frac{1}{2} \mathbf{B}_M \cdot \mathbf{M} - \mathbf{B}_a \cdot \mathbf{M} - \mathbf{B}_J \cdot \mathbf{M} \right]$$

$$U(\mathbf{M}) = \int_0^{\mathbf{M}} d\mathbf{M}' \cdot \mathbf{B}(\mathbf{M}')$$

**Problem restricted to
the magnetic material volume**

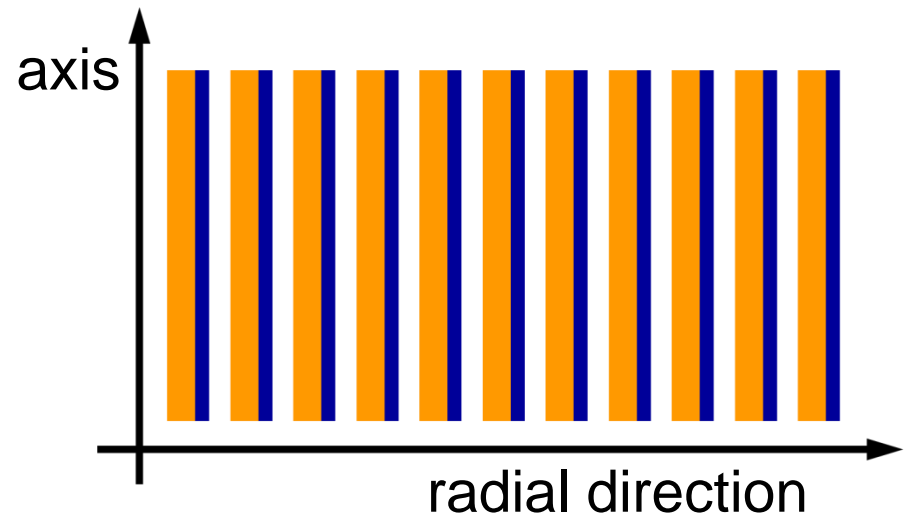
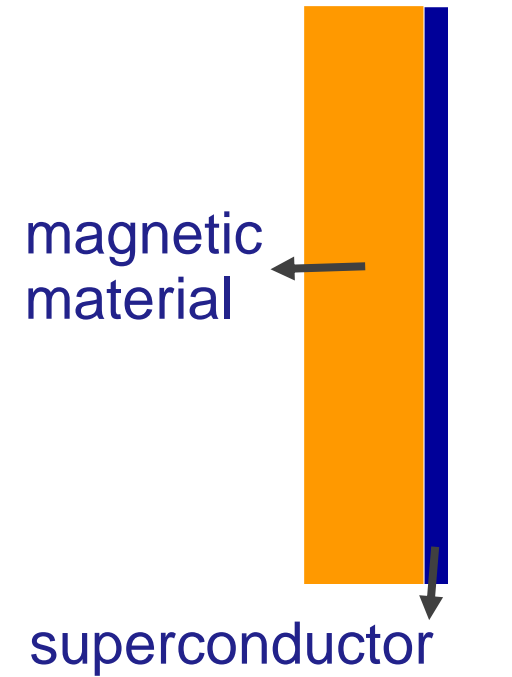
**Functionals for magnetic material and superconductor
solved iteratively**

Superconductor with non-linear magnetic substrate



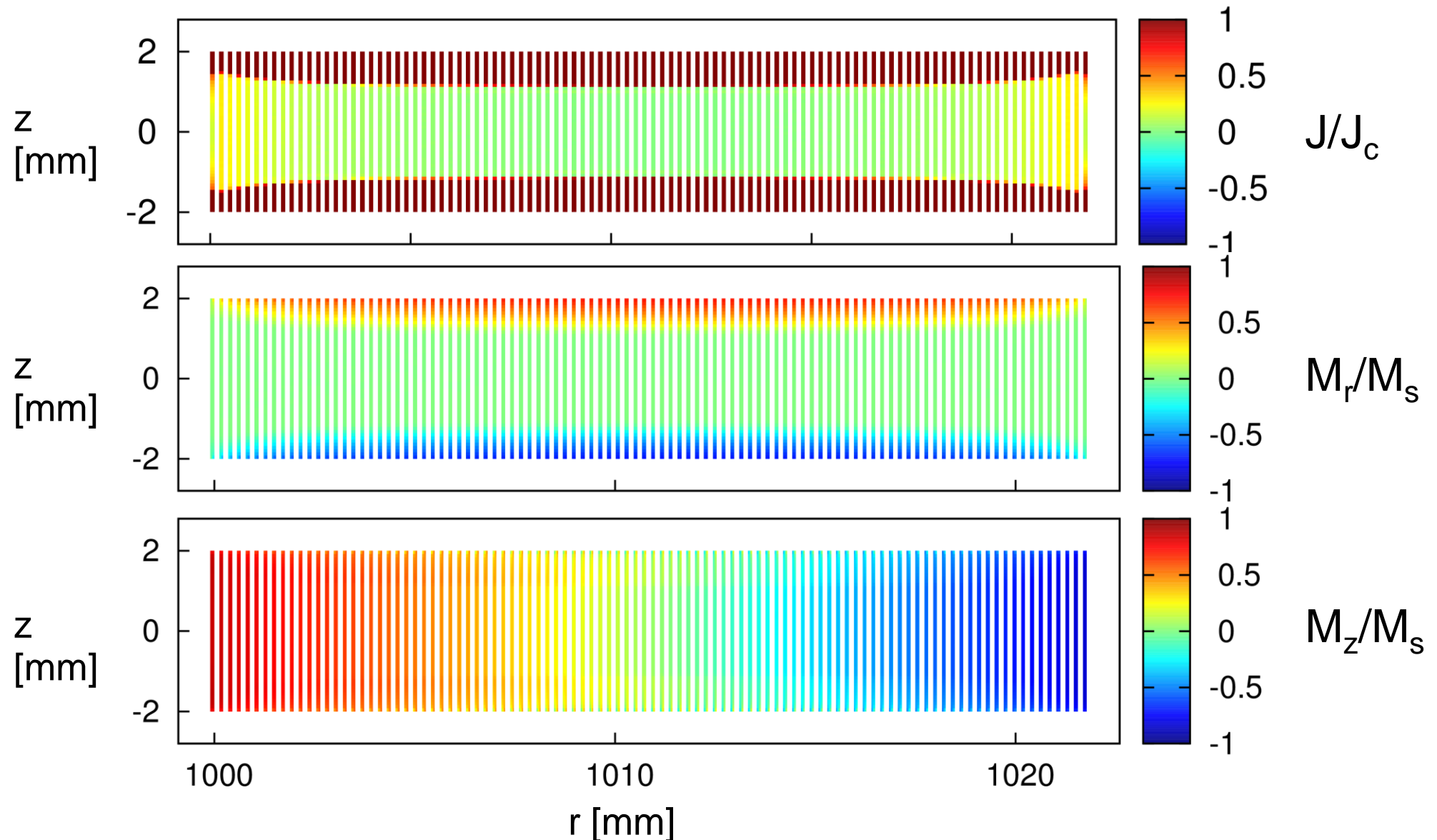
saturation $\mu_0 M$
300 mT

initial
susceptibility
500



Magnetic substrate saturates in part of the coil

100 turns, 50% of critical current



Conclusions

Cross-sectional variational method

Results agree with experiments : **transformer**

Models coils with more than

10 000 turns for real cross-section

40 000 turns for continuous approximation

**Up to half million elements
in the superconductor**

High potential for 3D modelling

3D modelling

Novel variational principle in T formulation

Takes force-free effects into account

Thin films:

**Tilted magnetic field
changes current patterns**

Bulk samples:

3D current penetration

**Significant vertical component
due to shape effects**

**Full power of the method
still not achieved!**

Non-linear magnetic material

3D variational principle

Restricts to the material volume

**Modelled coils with magnetic
substrate for one hundred turns**

Variational methods are suitable for power and magnet applications

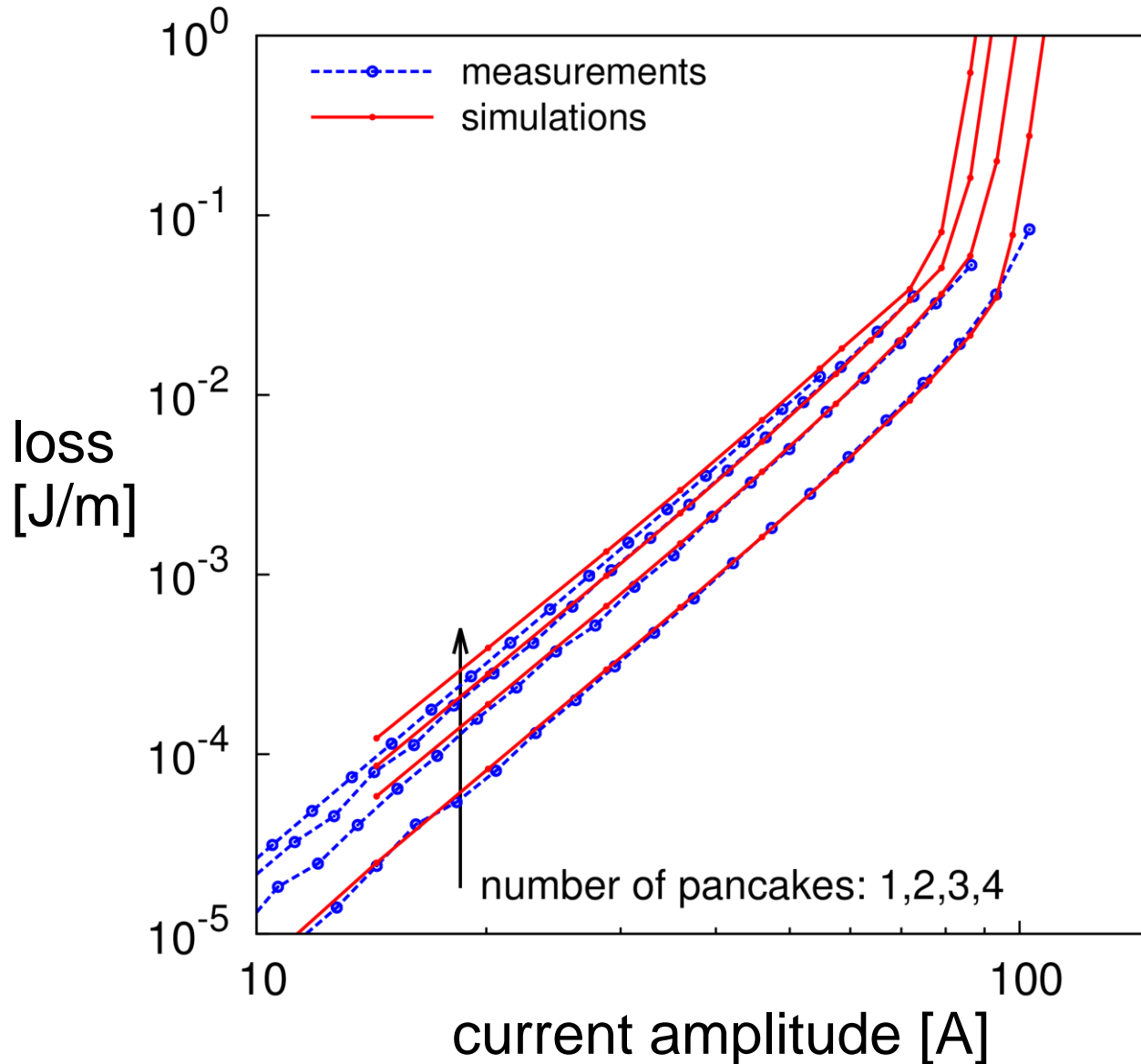
**Thank you
for your attention!**

**Would you like to
know more?**

Talk available at [**zenodo.org**](https://zenodo.org)

AC loss in test coils agrees with experiments

E Pardo et al. DOI: 10.1088/0953-2048/28/4/044003



Magnetic field dependent J_c

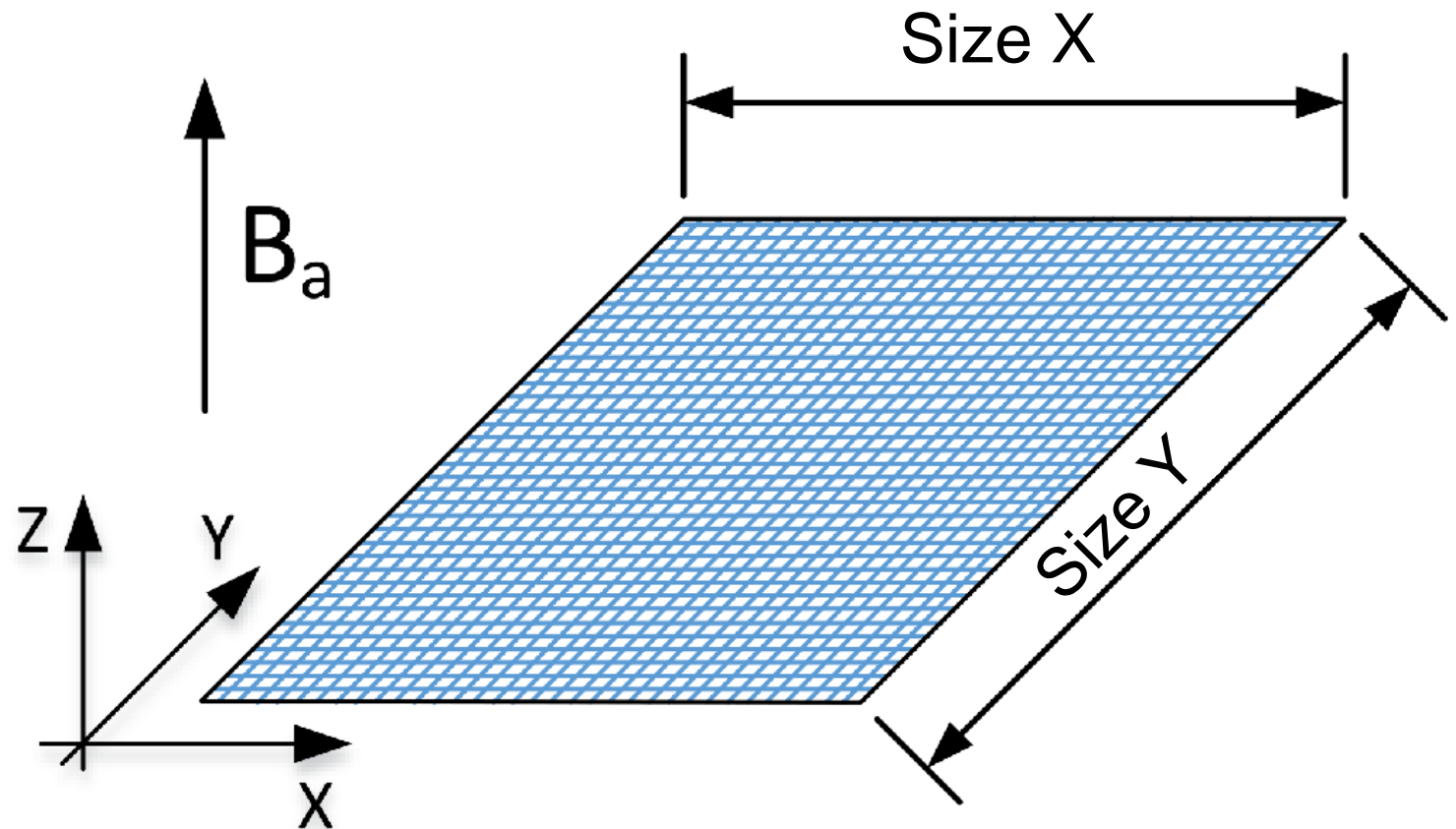
Magnetic field dependent power-law exponent

Thin surface

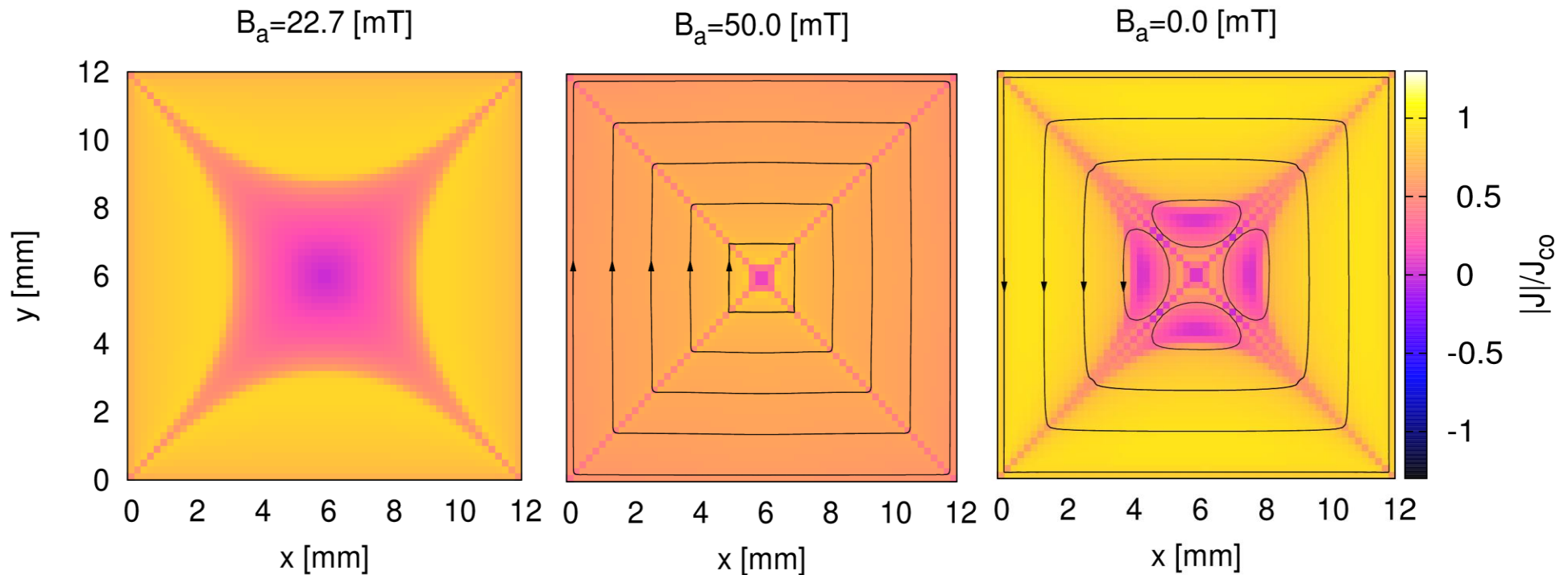
Frequency: **50 Hz** sinusoidal

Power-law exponent: **30**

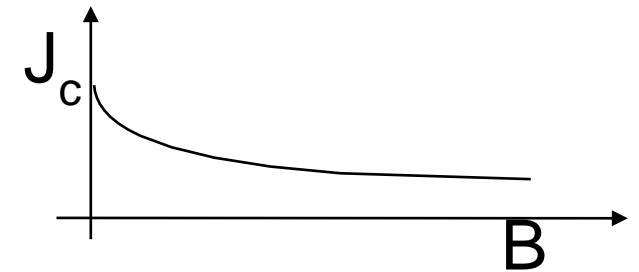
$J_c = 10^{10} \text{ A/m}^2$



J_c(B) dependence



Same penetration of \mathbf{J} as constant \mathbf{J}_c



\mathbf{J} decreased because of \mathbf{B} (Kim model)

$$J_c(B) = \frac{J_{co}}{\left(1 + \frac{B}{B_0}\right)^m}$$

Power loss

